

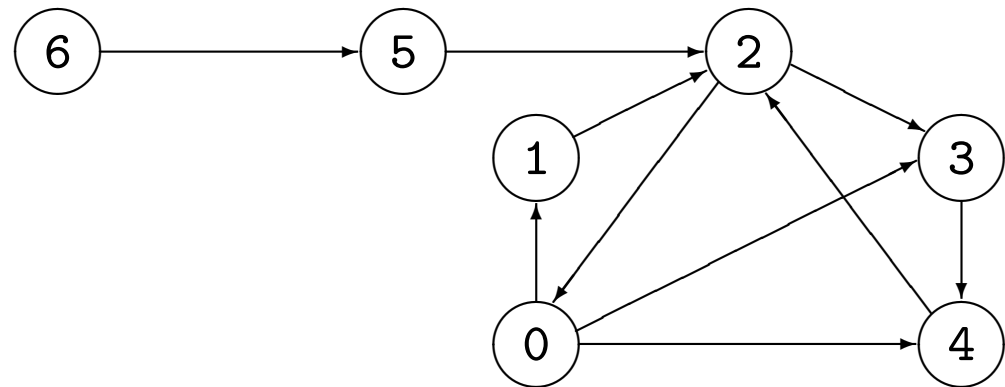
Capítulo IV

Percurso em Largura (num grafo orientado ou não orientado)

Percurso em Largura

0

Ordem:



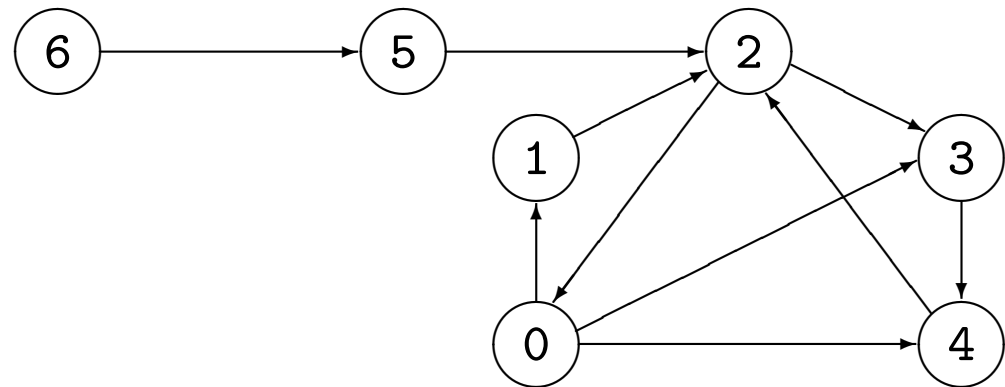
Percurso em Largura

0

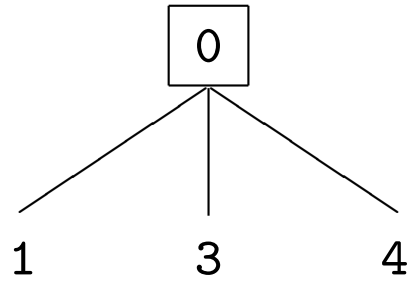
Ordem:

FIFO:

0



Percurso em Largura

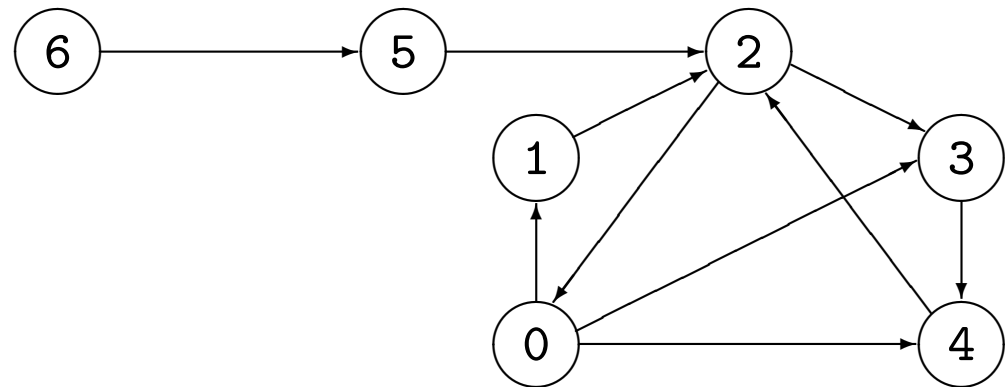


Ordem:

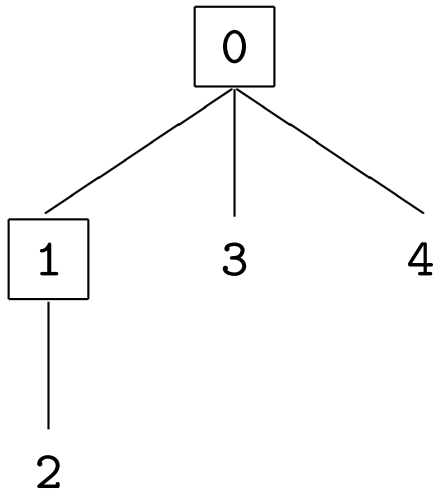
0

FIFO:

1 3 4



Percurso em Largura

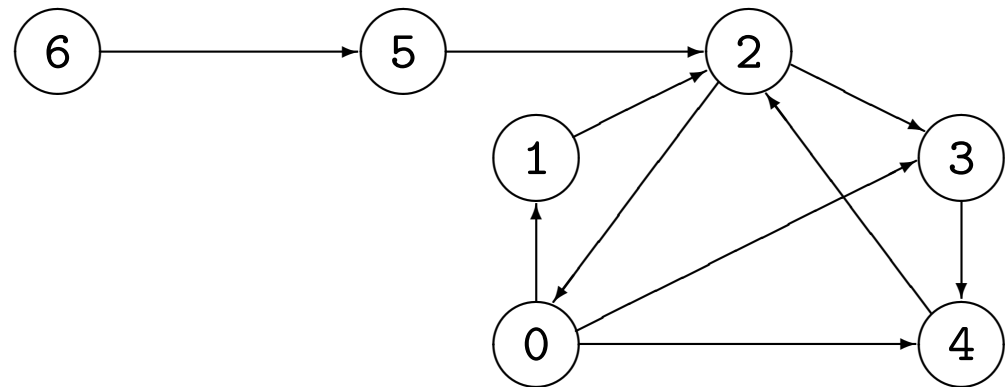


Ordem:

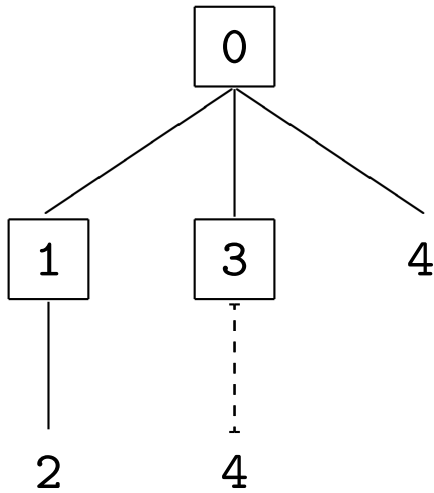
0 1

FIFO:

3 4 2



Percurso em Largura

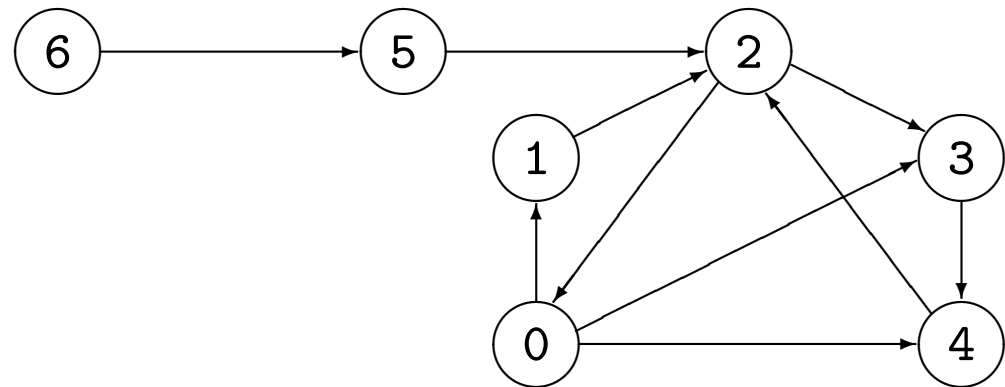


Ordem:

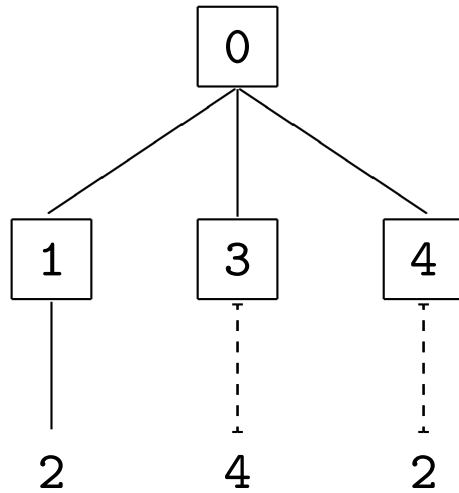
0 1 3

FIFO:

4 2



Percurso em Largura

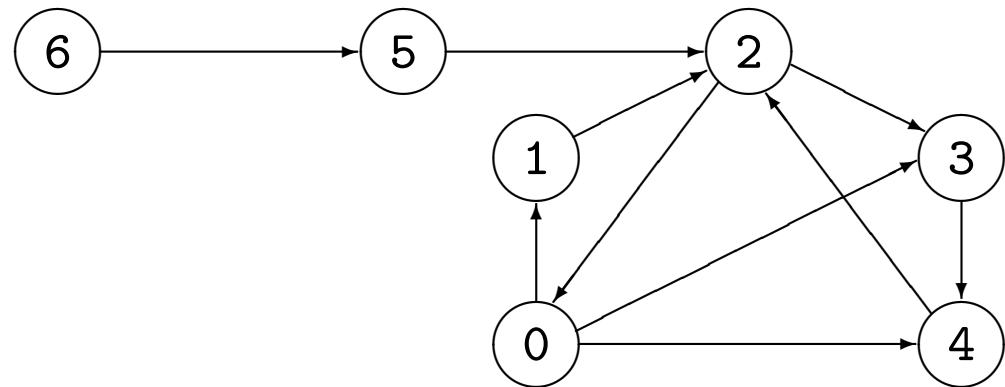


Ordem:

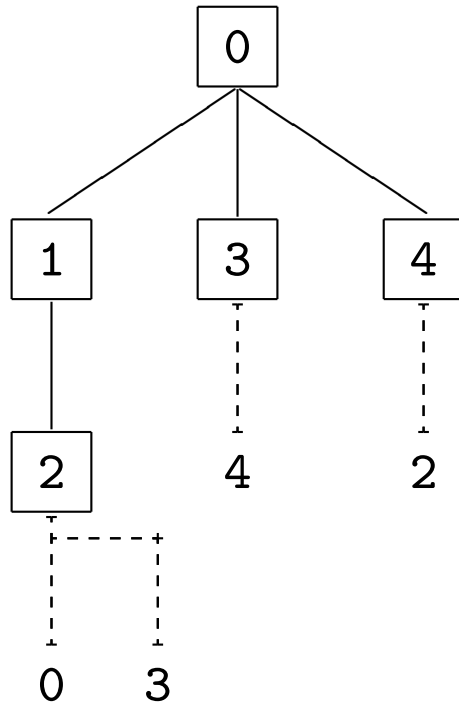
0 1 3 4

FIFO:

2



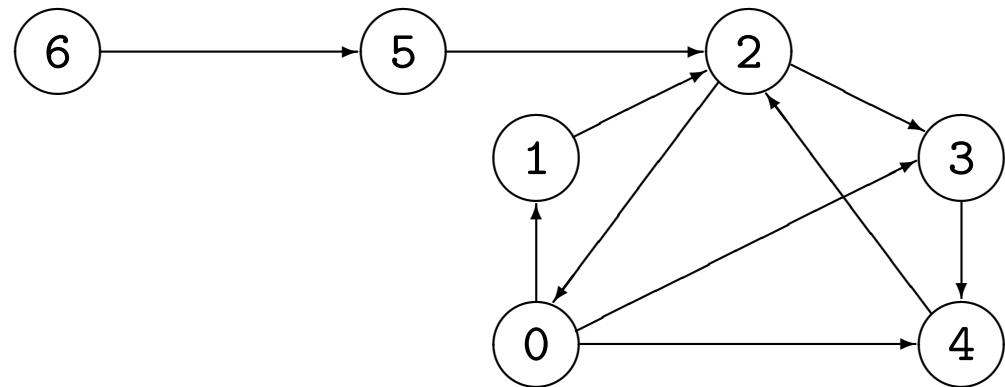
Percurso em Largura



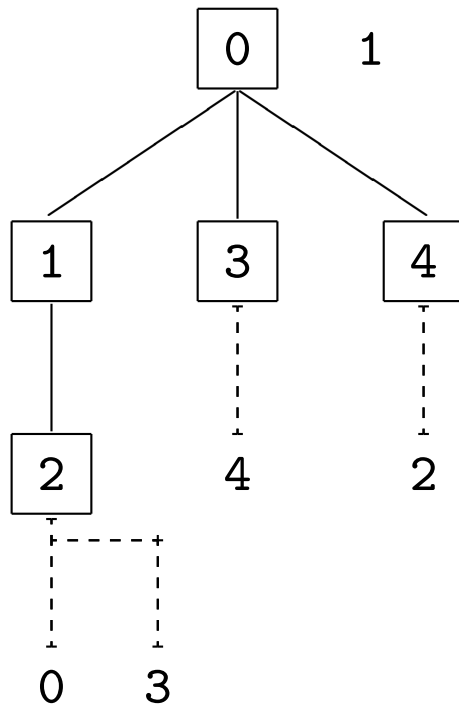
Ordem:

0 1 3 4 2

FIFO:

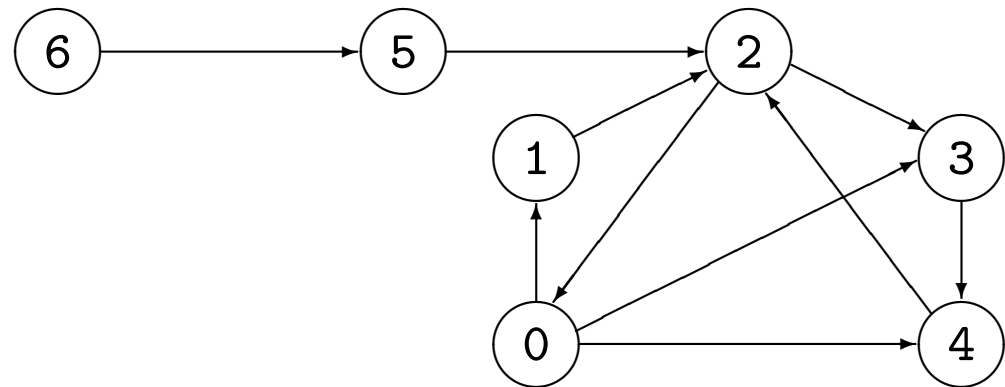


Percurso em Largura

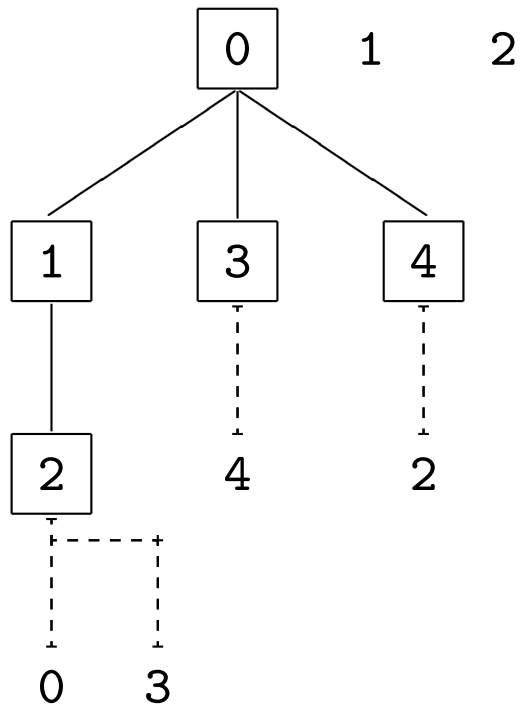


Ordem:

0 1 3 4 2

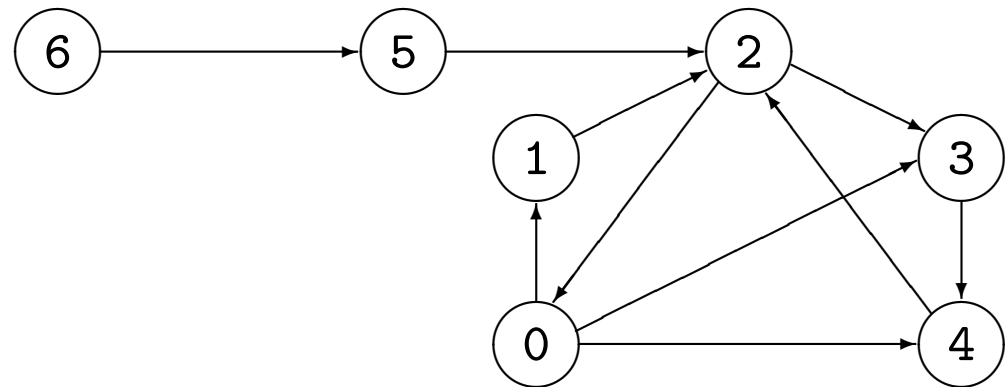


Percurso em Largura

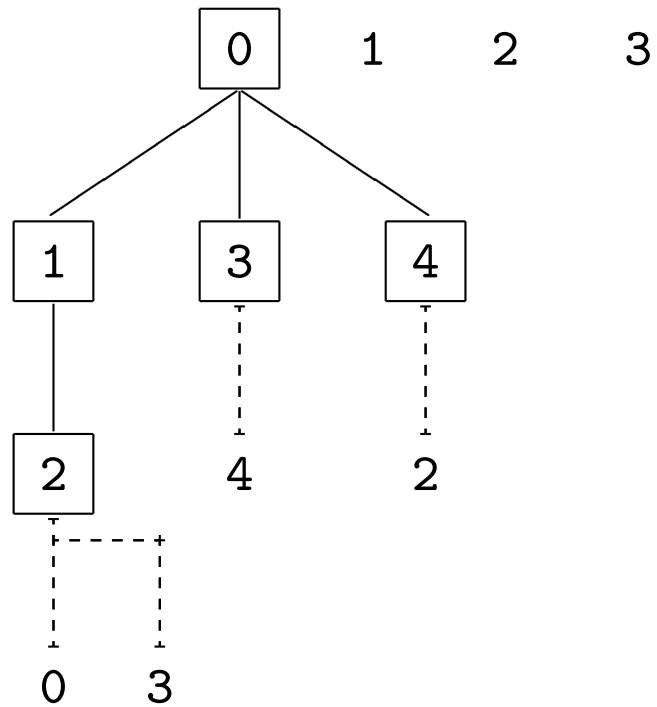


Ordem:

0 1 3 4 2

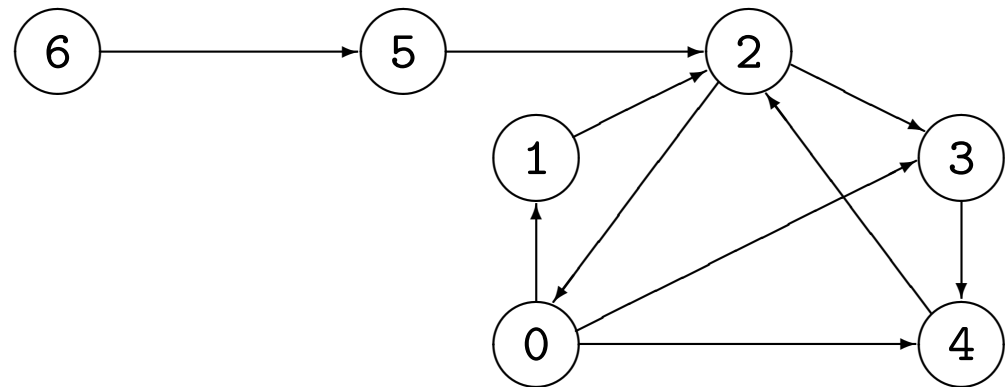


Percurso em Largura

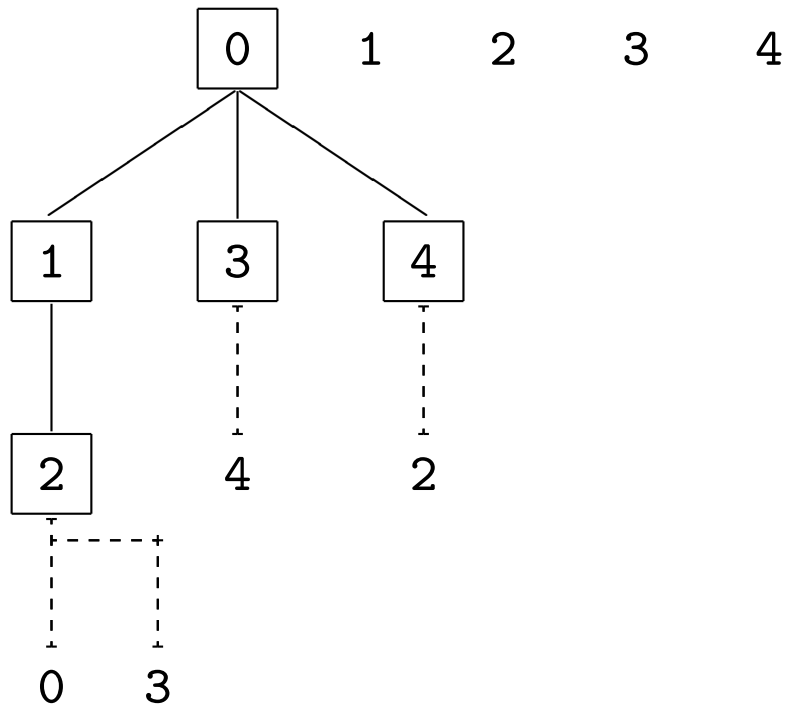


Ordem:

0 1 3 4 2

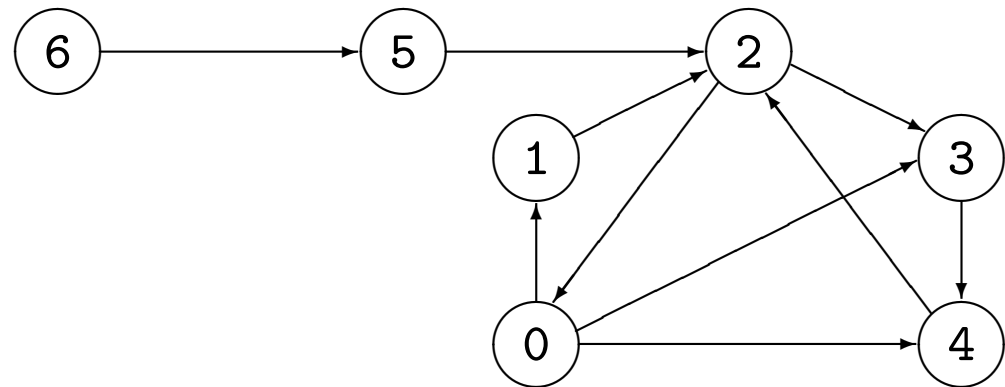


Percurso em Largura

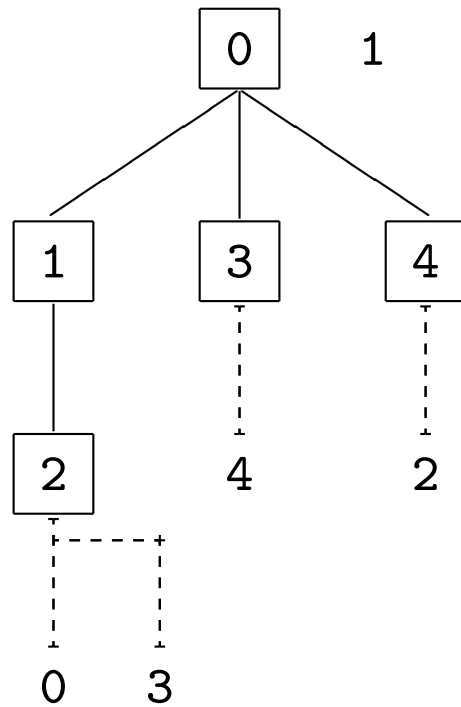


Ordem:

0 1 3 4 2

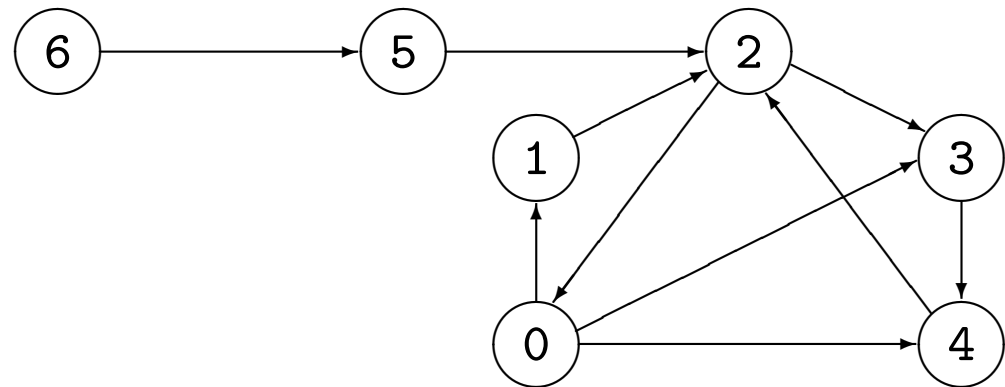


Percurso em Largura

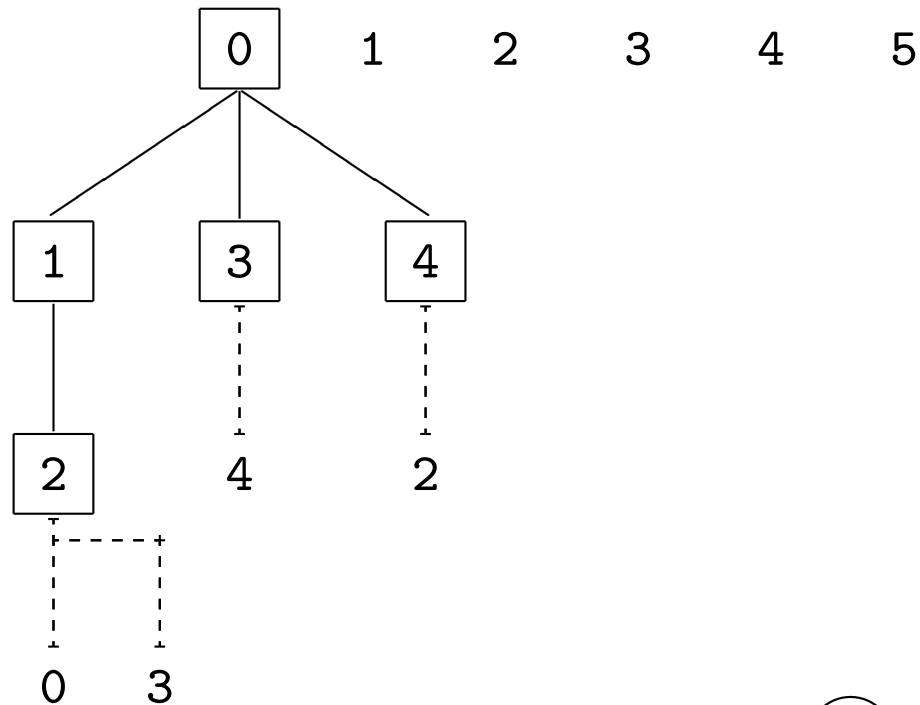


Ordem:

0 1 3 4 2



Percurso em Largura

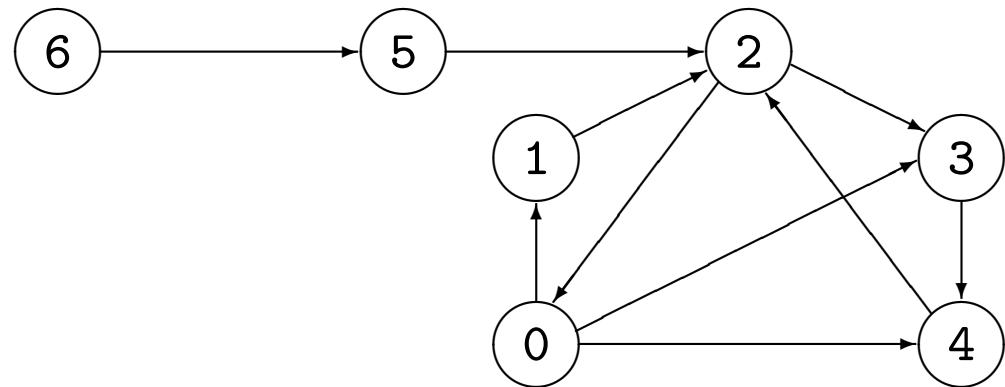


Ordem:

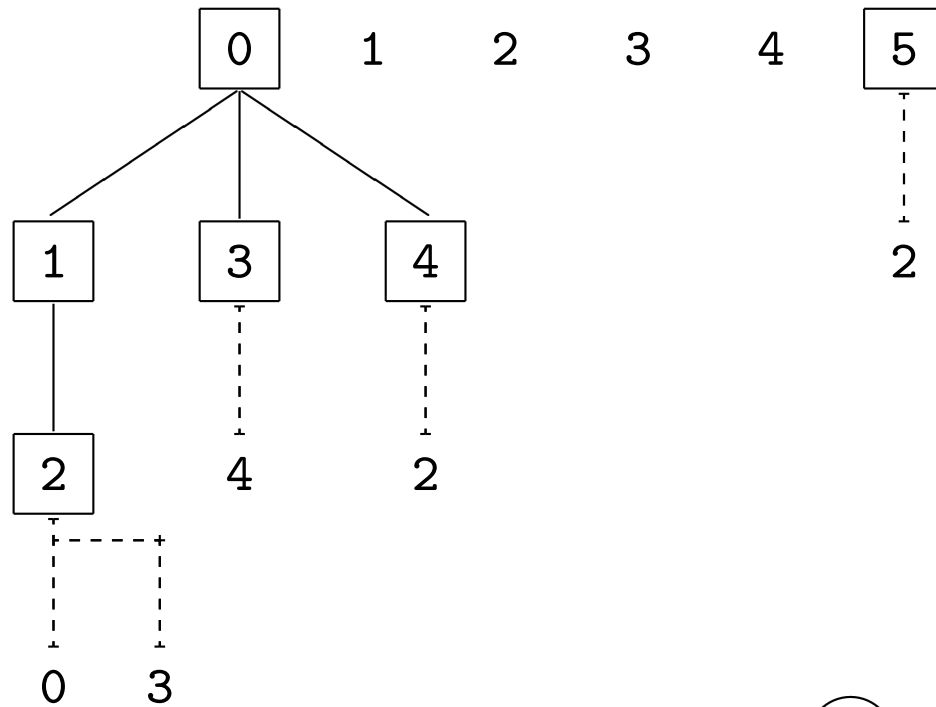
0 1 3 4 2

FIFO:

5



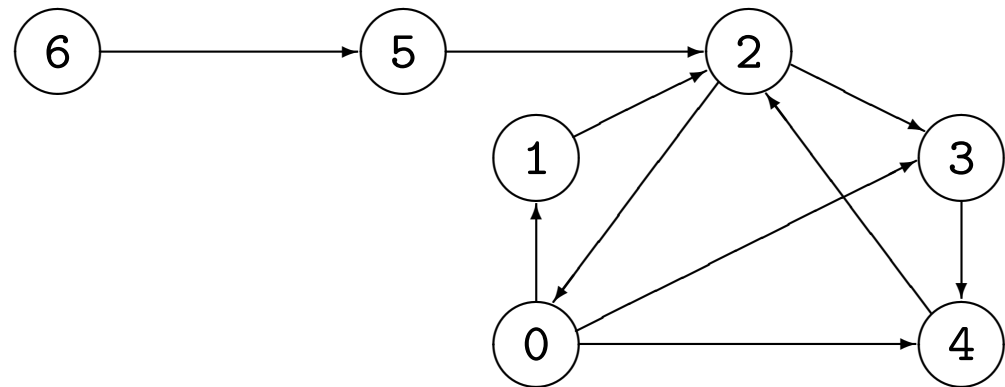
Percurso em Largura



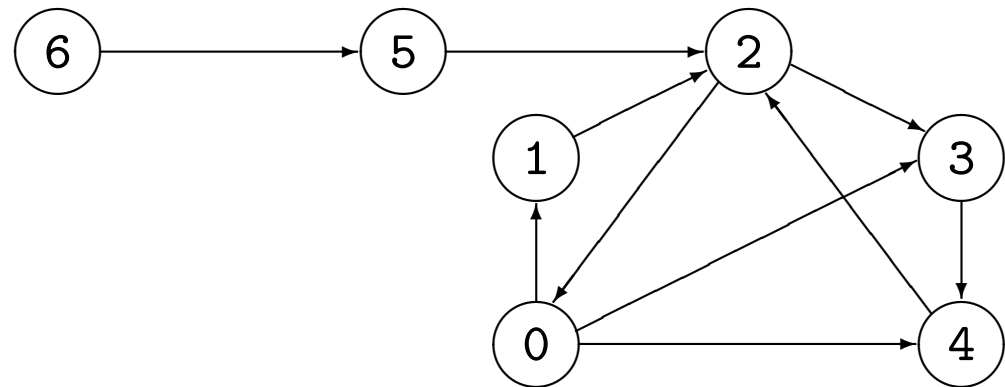
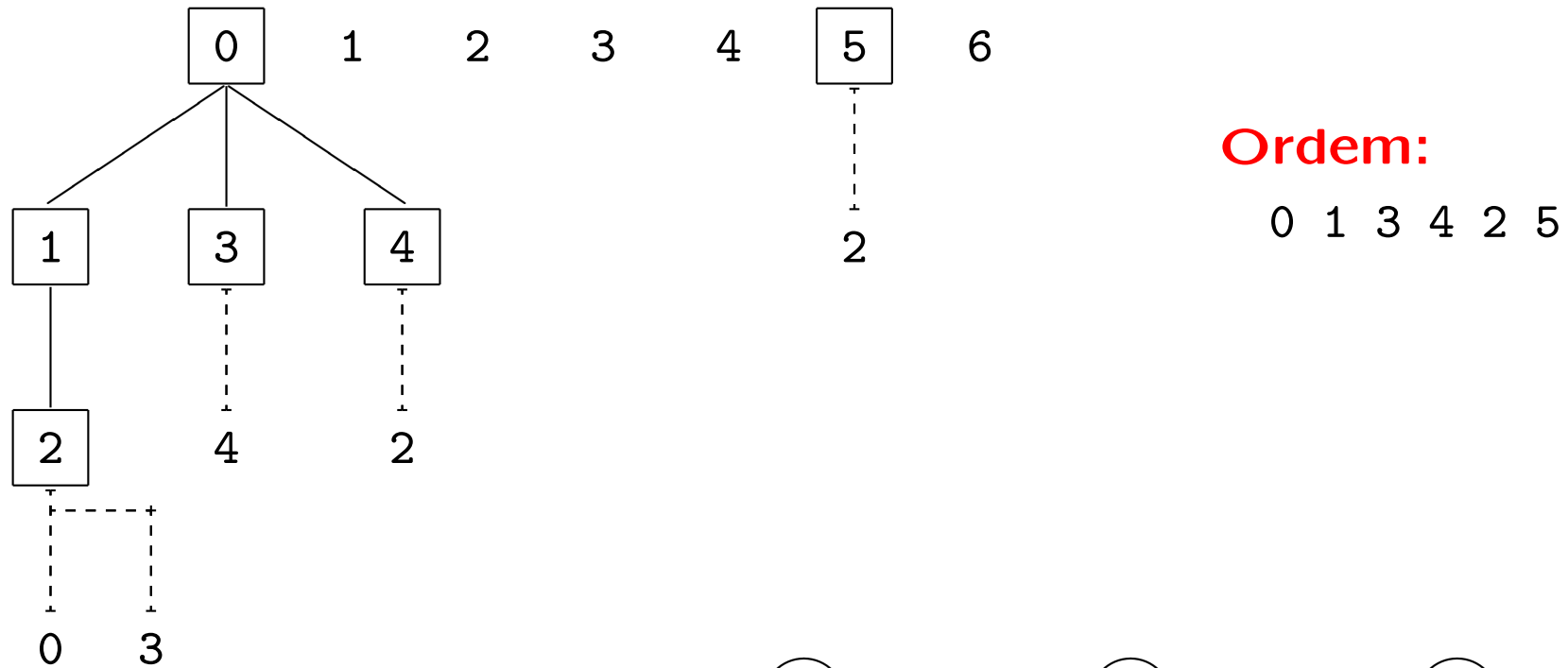
Ordem:

0 1 3 4 2 5

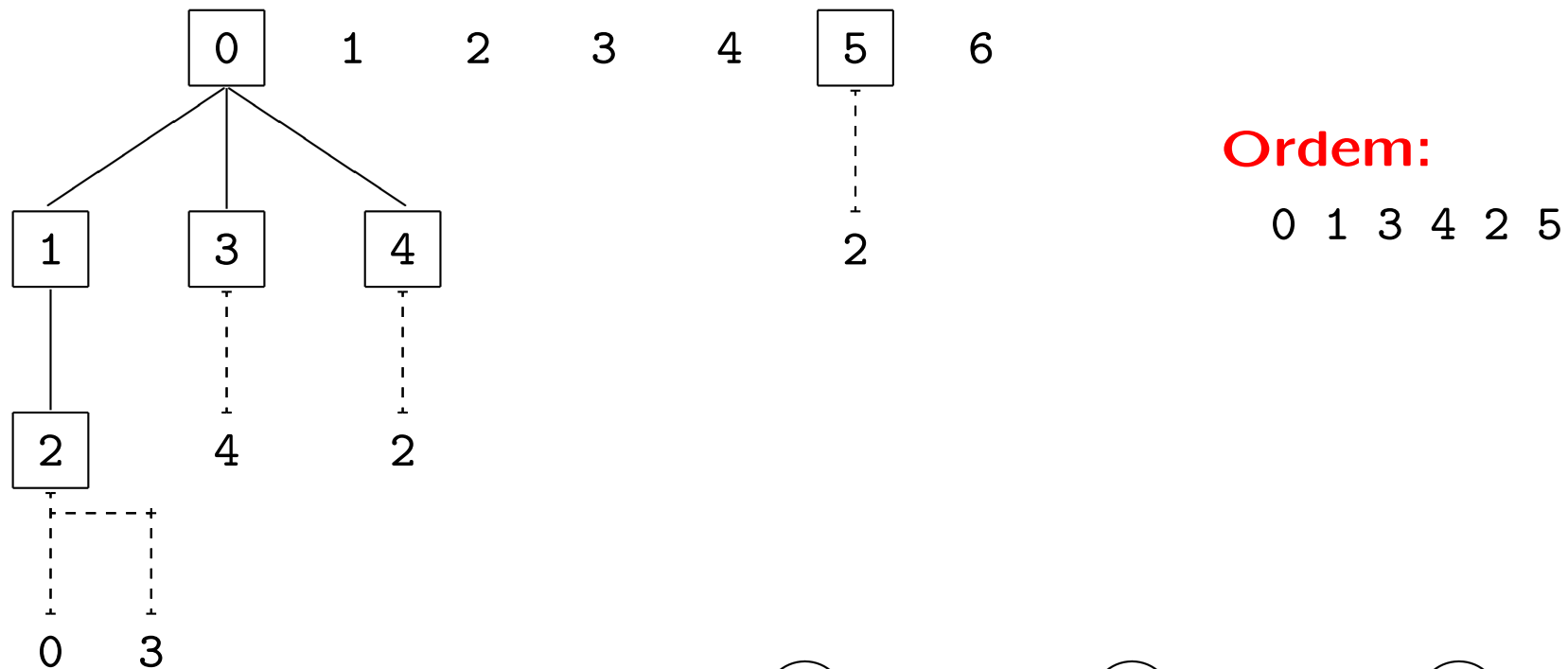
FIFO:



Percurso em Largura



Percurso em Largura

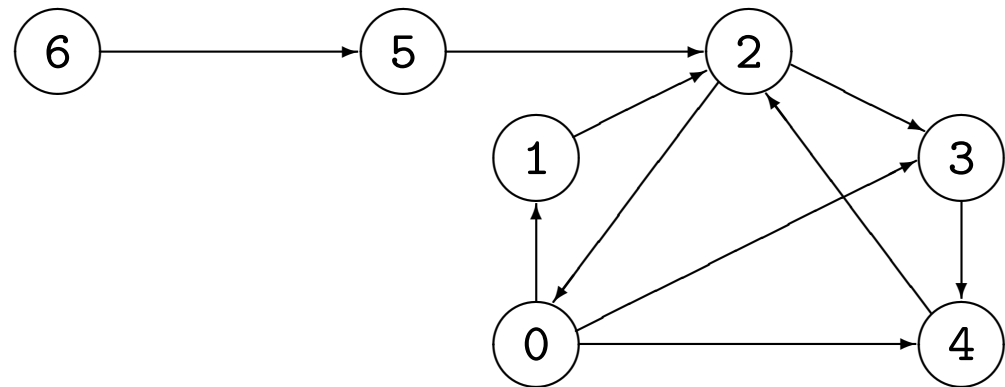


Ordem:

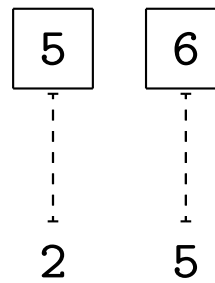
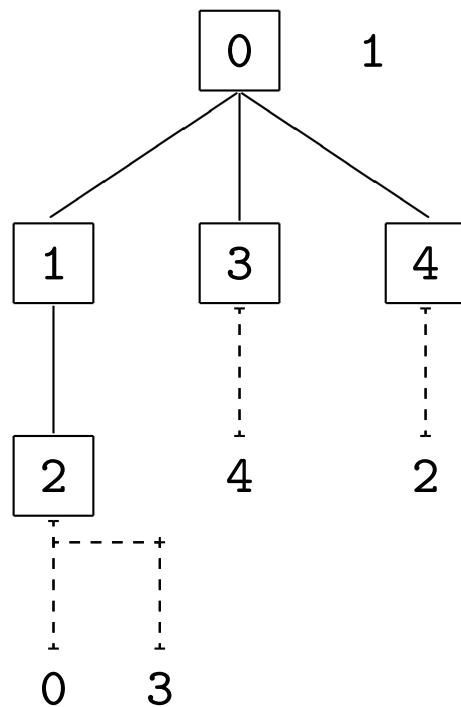
0 1 3 4 2 5

FIFO:

6



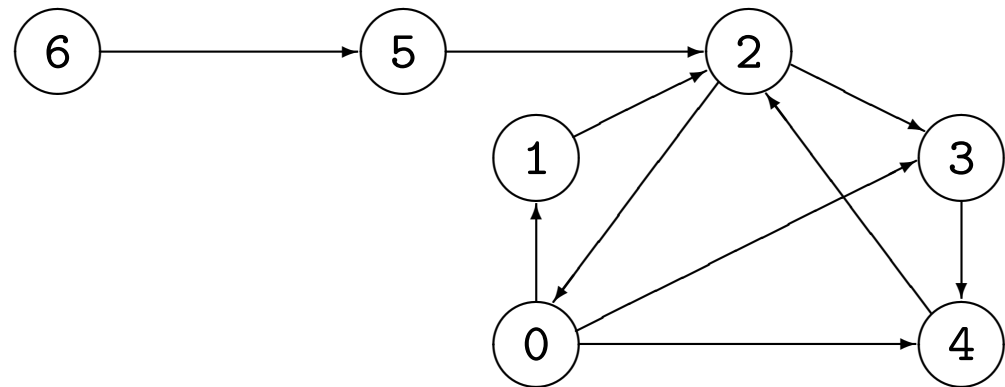
Percurso em Largura



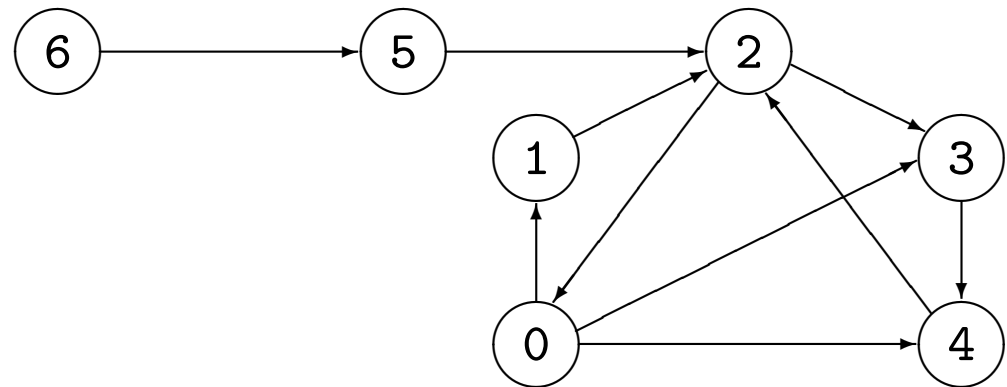
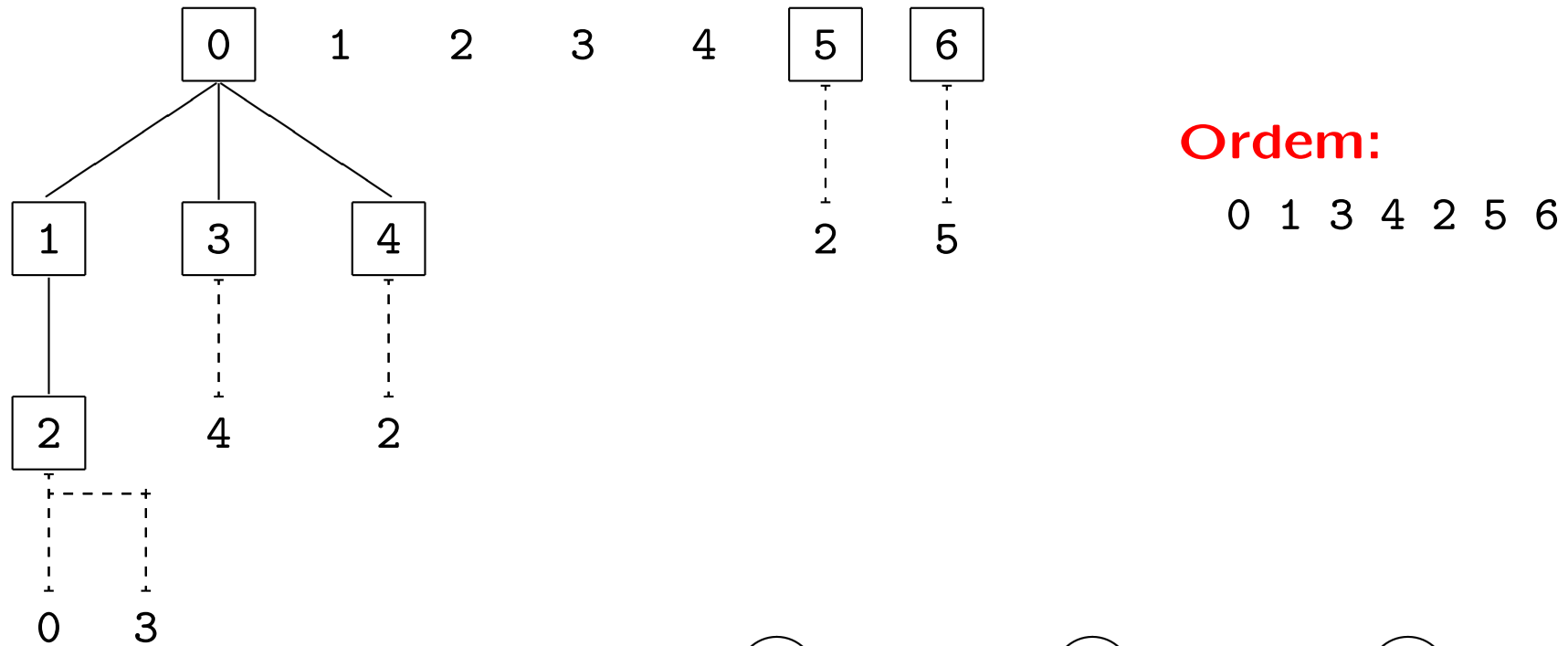
Ordem:

0 1 3 4 2 5 6

FIFO:



Percurso em Largura



Percurso em Largura

(Breadth-First Search Traversal)

```
void bfsTraversal( Digraph graph ) {  
    boolean[] found = new boolean[ graph.numNodes() ];  
    for every Node v in graph.nodes()  
        found[v] = false;  
    for every Node v in graph.nodes()  
        if ( !found[v] )  
            bfsExplore(graph, found, v);  
}
```

Árvore em Largura (iterativo)

```
void bfsExplore( Digraph graph,  boolean[] found,  Node root ) {  
    Queue<Node> waiting = new QueueIn...<>(?  
    waiting.enqueue(root);  
    found[root] = true;  
    do {  
        Node node = waiting.dequeue();  
        // PROCESS(node)  
        for every Node v in graph.outAdjacentNodes(node)  
            if ( !found[v] ) {  
                waiting.enqueue(v);  
                found[v] = true;  
            }  
    }  
    while ( !waiting.isEmpty() );  
}
```

Complexidade de **bfsExplore**

- **Por cada vértice (w)**
 - Se $\text{PROCESS}(w)$ não for constante, considerar o seu custo
 - Remove-se w da fila $\Theta(1)$
 - Iteram-se os sucessores de w
 - * Grafo em matriz de adjacências $\Theta(|V|)$
 - * Grafo em vetor de listas de adjacências (suc.) $\Theta(|\text{Suc}(w)|)$
 - Inserem-se os suc. nunca inseridos de w na fila $O(|\text{Suc}(w)|)$
- **Custo de todas as execuções ($\# \text{DEQUEUE} = \# \text{ENQUEUE}$)**
 - Grafo em matriz de adjacências $\Theta(|V|^2)$
 - Grafo em vetor de listas de adjacências (suc.) $\Theta(|V| + |A|)$

Num grafo orientado, $\sum_{w \in V} |\text{Suc}(w)| = |A|$.

Num grafo não orientado, $\sum_{w \in V} |\text{Suc}(w)| = 2 \times |A|$.

Complexidade Temporal de **bfsTraversal** (se enqueue, dequeue e isEmpty de Queue forem $\Theta(1)$)

Grafo em matriz de adjacências

Criação do vetor found	$\Theta(1)$
1º ciclo (inicialização do vetor found)	$\Theta(V)$
2º ciclo (ignorando execuções de bfsExplore)	$\Theta(V)$
Execuções de bfsExplore	$\Theta(V ^2)$
TOTAL	$\Theta(V ^2)$

Grafo em vetor de listas de adjacências (suc.)

Criação do vetor found	$\Theta(1)$
1º ciclo (inicialização do vetor found)	$\Theta(V)$
2º ciclo (ignorando execuções de bfsExplore)	$\Theta(V)$
Execuções de bfsExplore	$\Theta(V + A)$
TOTAL	$\Theta(V + A)$

Complexidade Espacial de **bfsTraversal**

Vetor found $\Theta(|V|)$

Fila waiting $O(|V|)$

TOTAL $\Theta(|V|)$