

## Introduction to Clustering

**Ludwig Krippahl**

# Introduction to Clustering

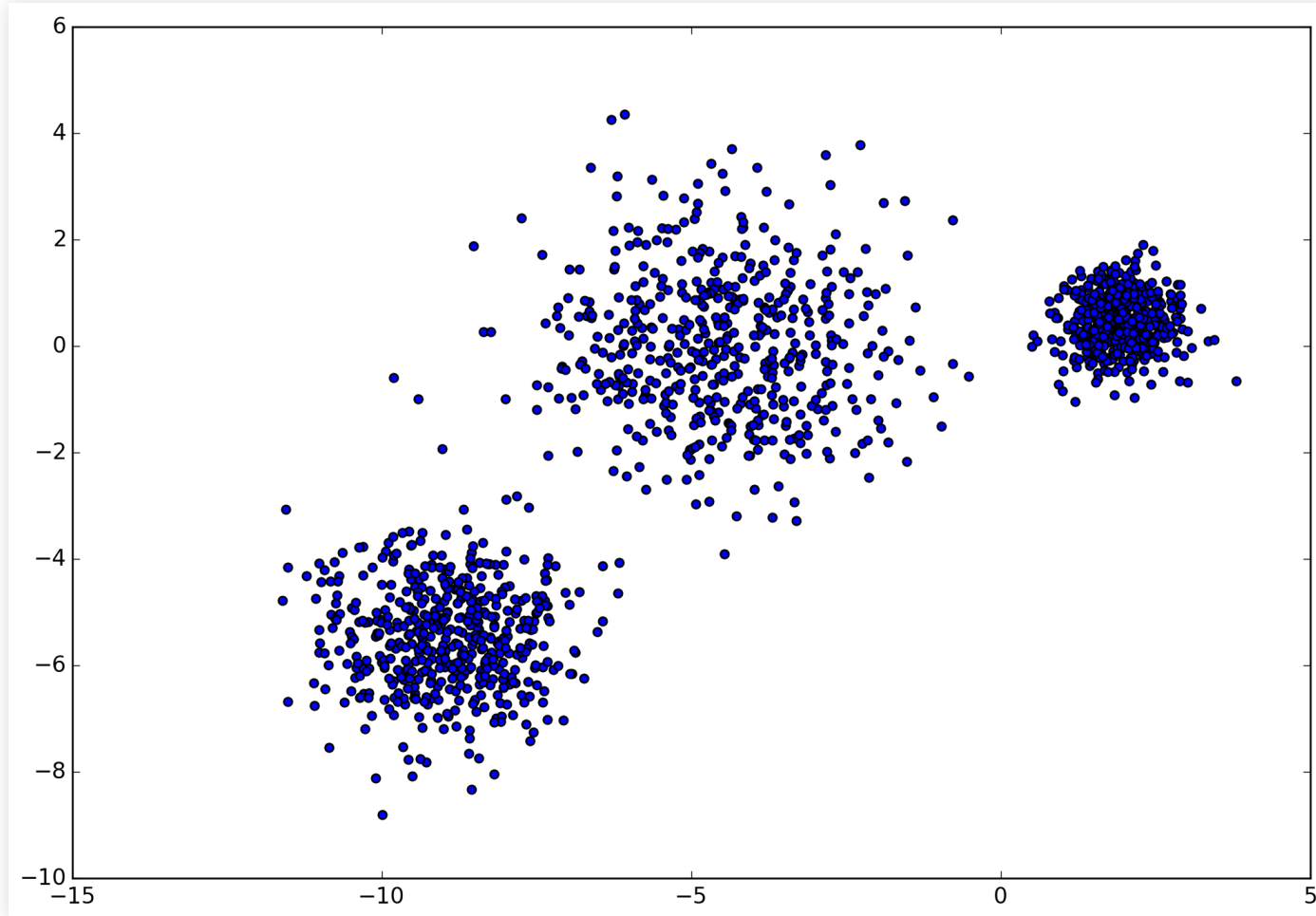
## Summary

- Introduction to clustering
- K-means and k-medoids
- A first (informal) look at Expectation-Maximization

## Clustering

# Clustering

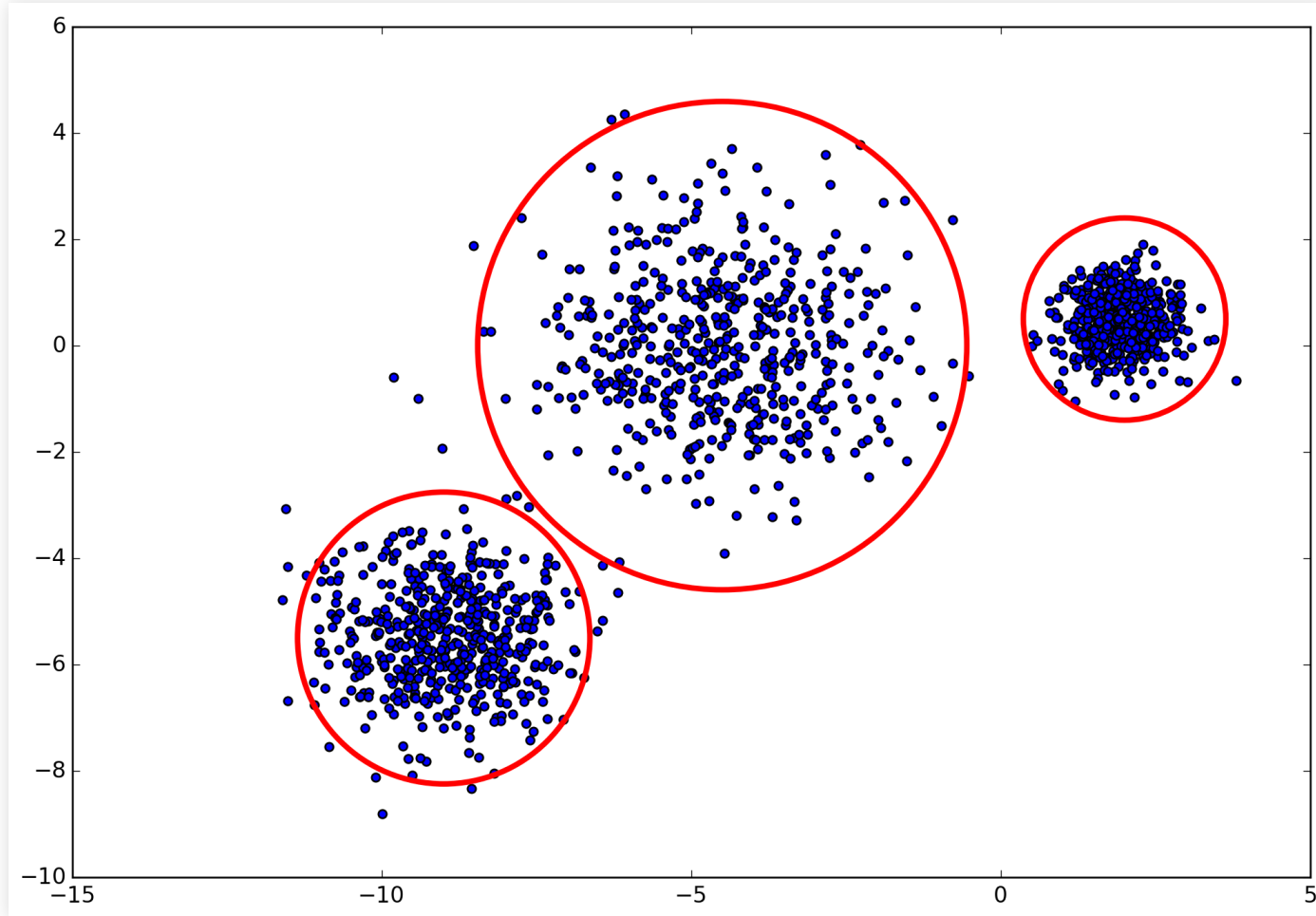
**Basic idea: Group similar examples together**





# Clustering

**Basic idea: Group similar examples together**



## Basic idea: Group similar examples together

- Min difference (or max similarity) within clusters
- Max difference (or min similarity) between clusters
- Clustering requires some measure of similarity or difference

## Why clustering?

- To help understand data and relations
  - Meaningful grouping is part of how we understand things
  - Clustering helps make sense of complex or abundant data
  - WWW searches, biology, climate, ...
  - Clustering can help identify meaningful groups
- To reduce data to relevant examples



# Clustering

## Identifying "Ghost Cities"



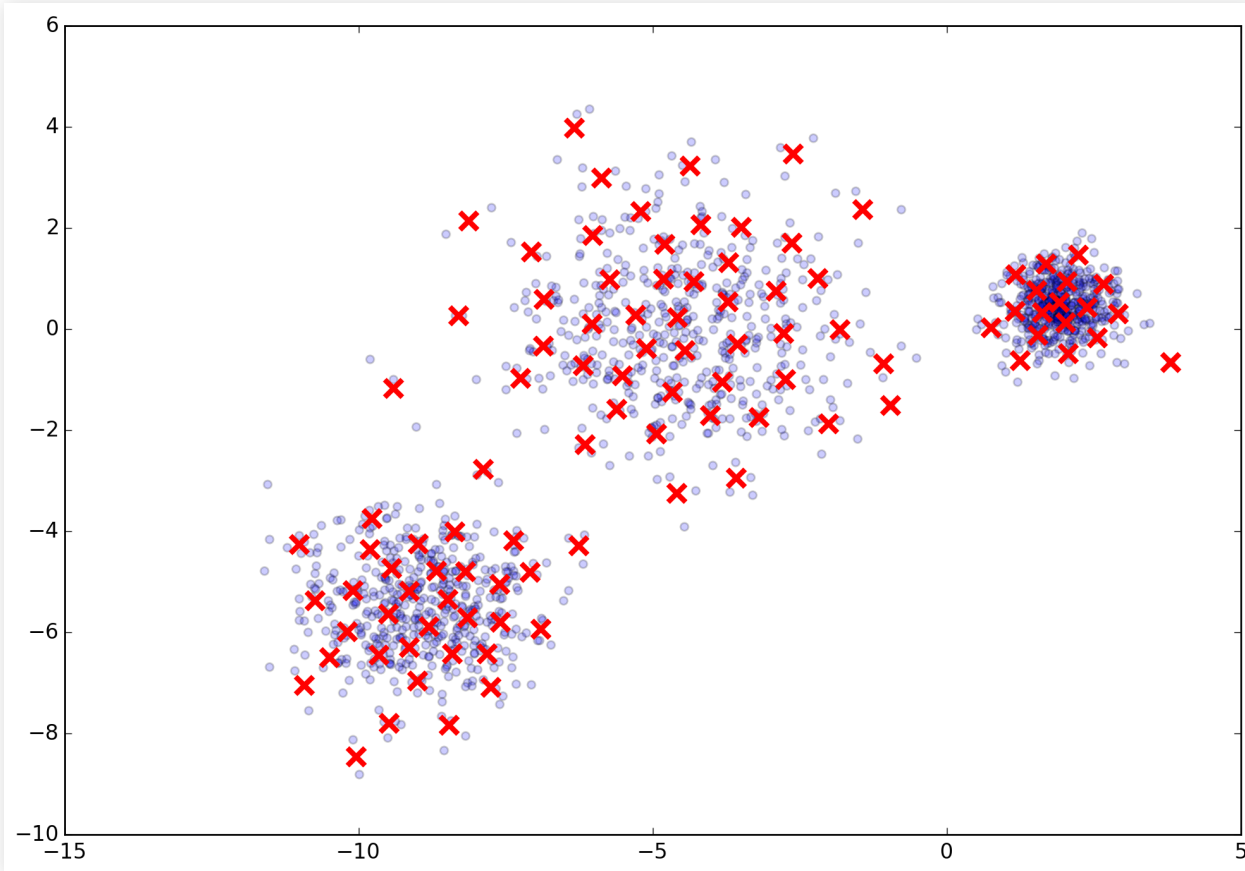
"Ghost Cities" Analysis [...]. Chi et. al, <http://arxiv.org/abs/1510.08505>

## Why clustering?

- To reduce (summarize) data:
  - Cluster prototypes abstract properties from groups and can be used to reduce the data set replacing all points in group
- Can improve performance of data analysis or classification (often quadratic on the number of examples)
  - Sumarizing, compressing, finding neighbours, image segmentation, etc

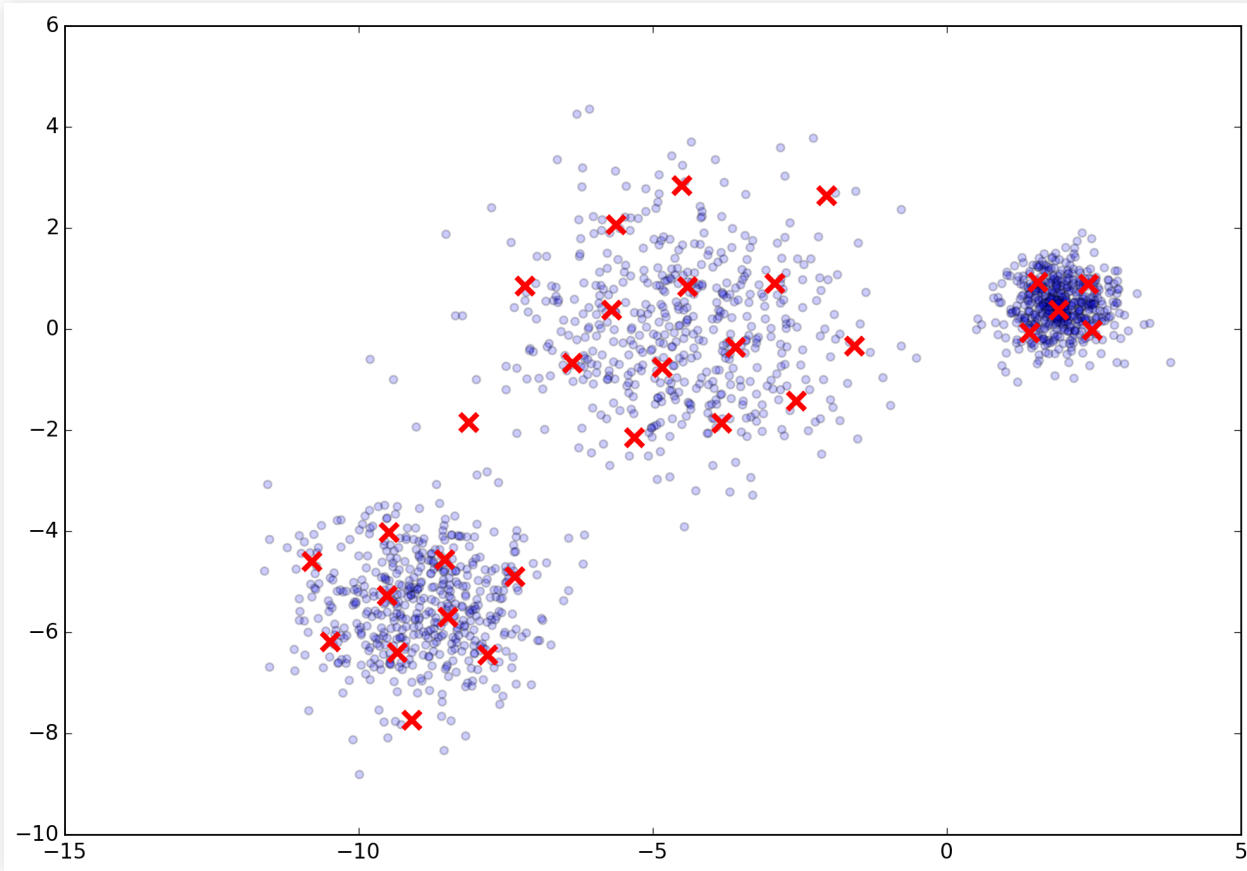
# Why clustering?

To reduce (summarize) data:



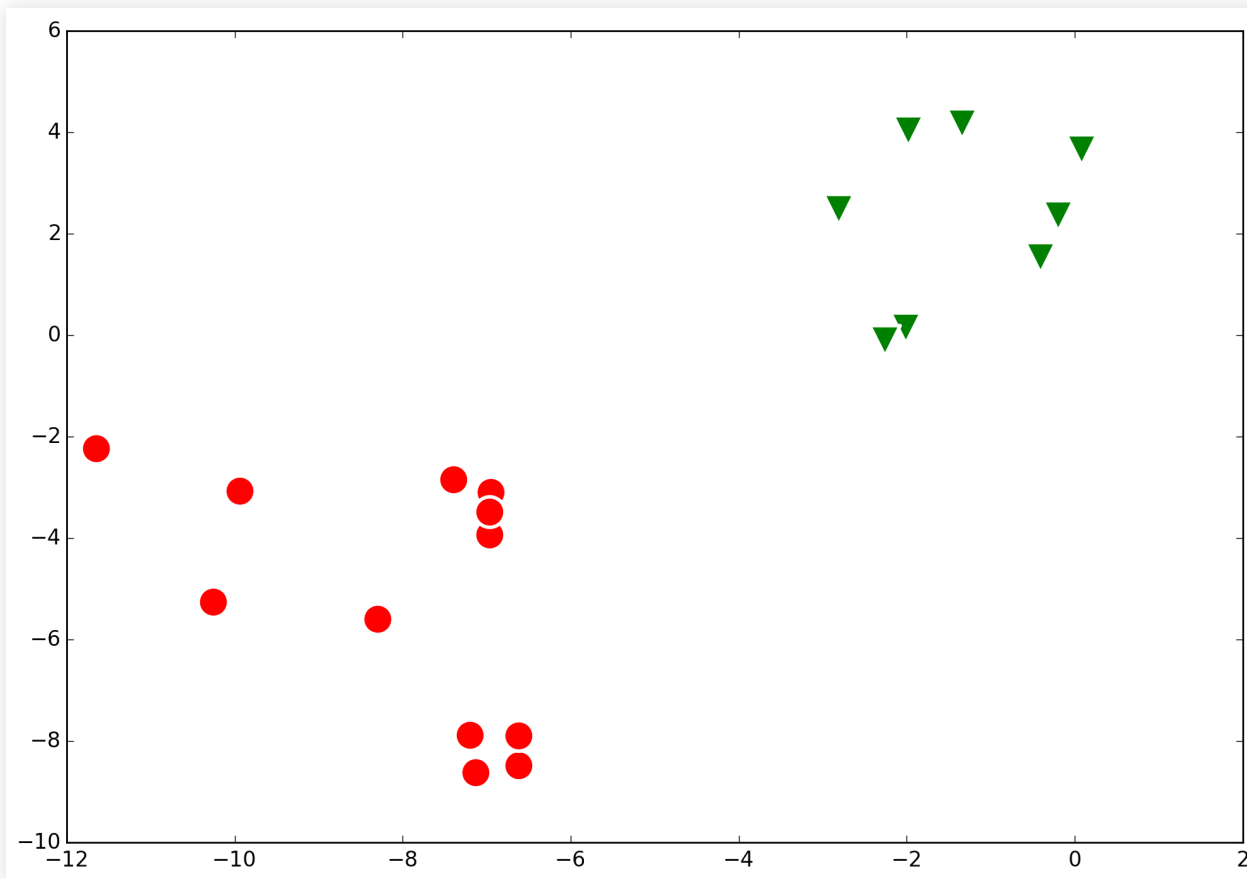
# Why clustering?

To reduce (summarize) data:



# Defining clusters

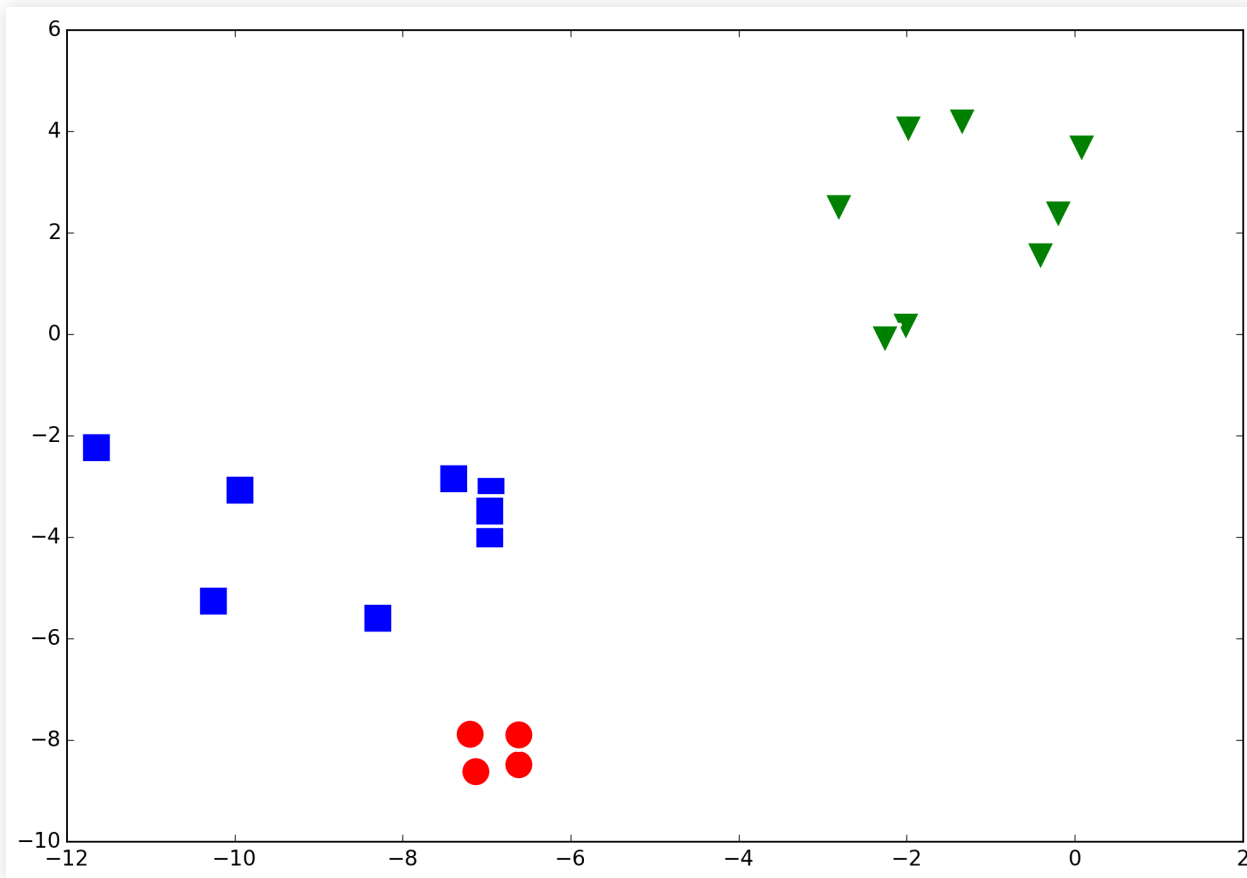
- Are there two clusters here?





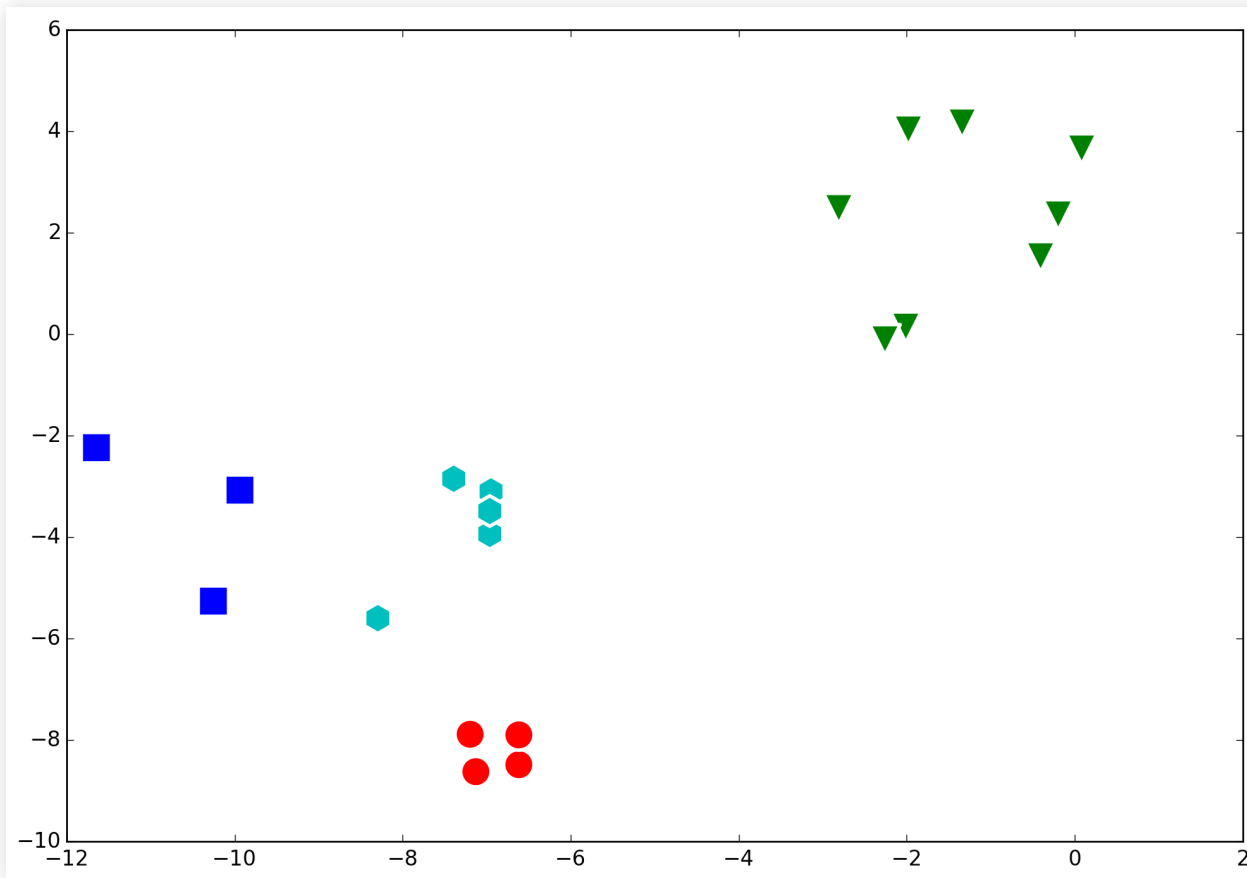
# Defining clusters

- Are there three clusters here?



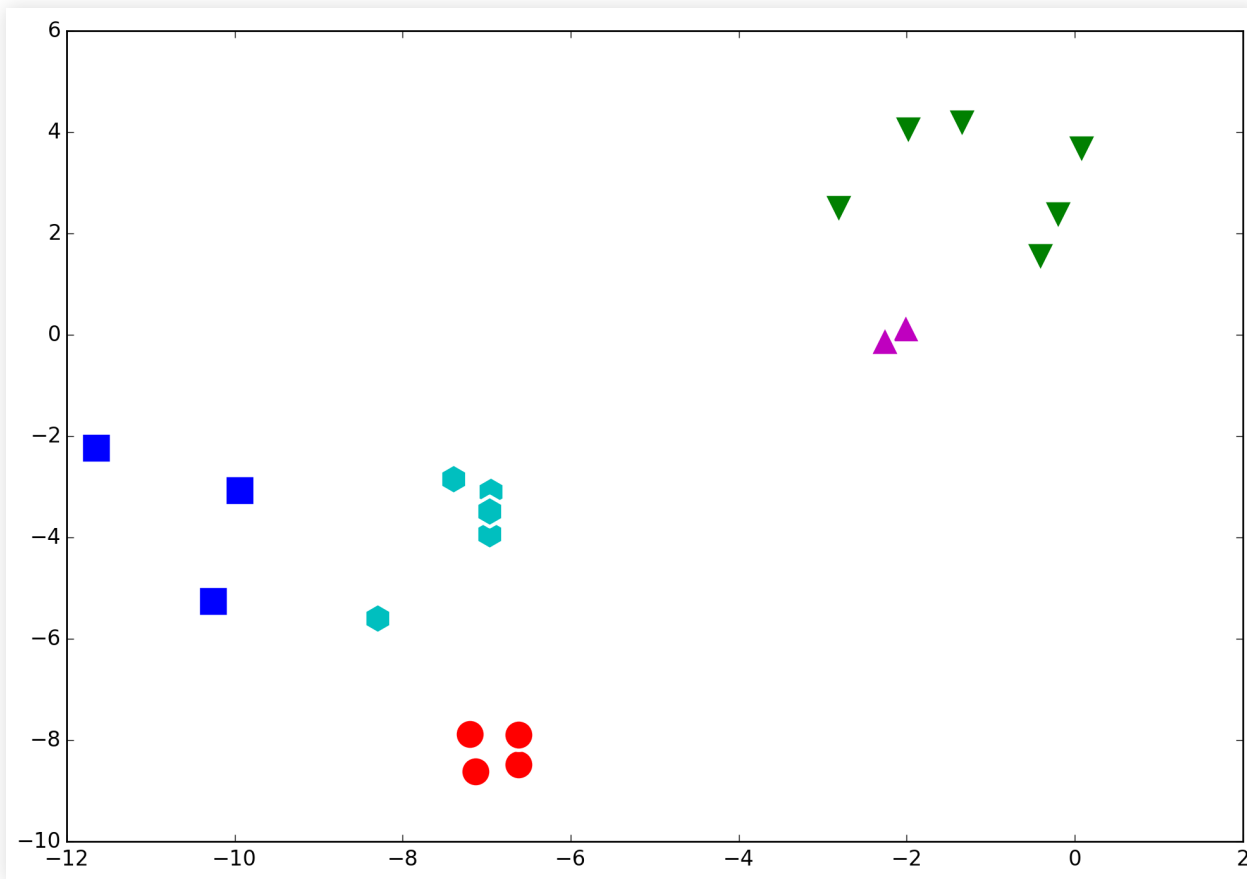
# Defining clusters

- Are there four clusters here?



# Defining clusters

- Are there five clusters here?



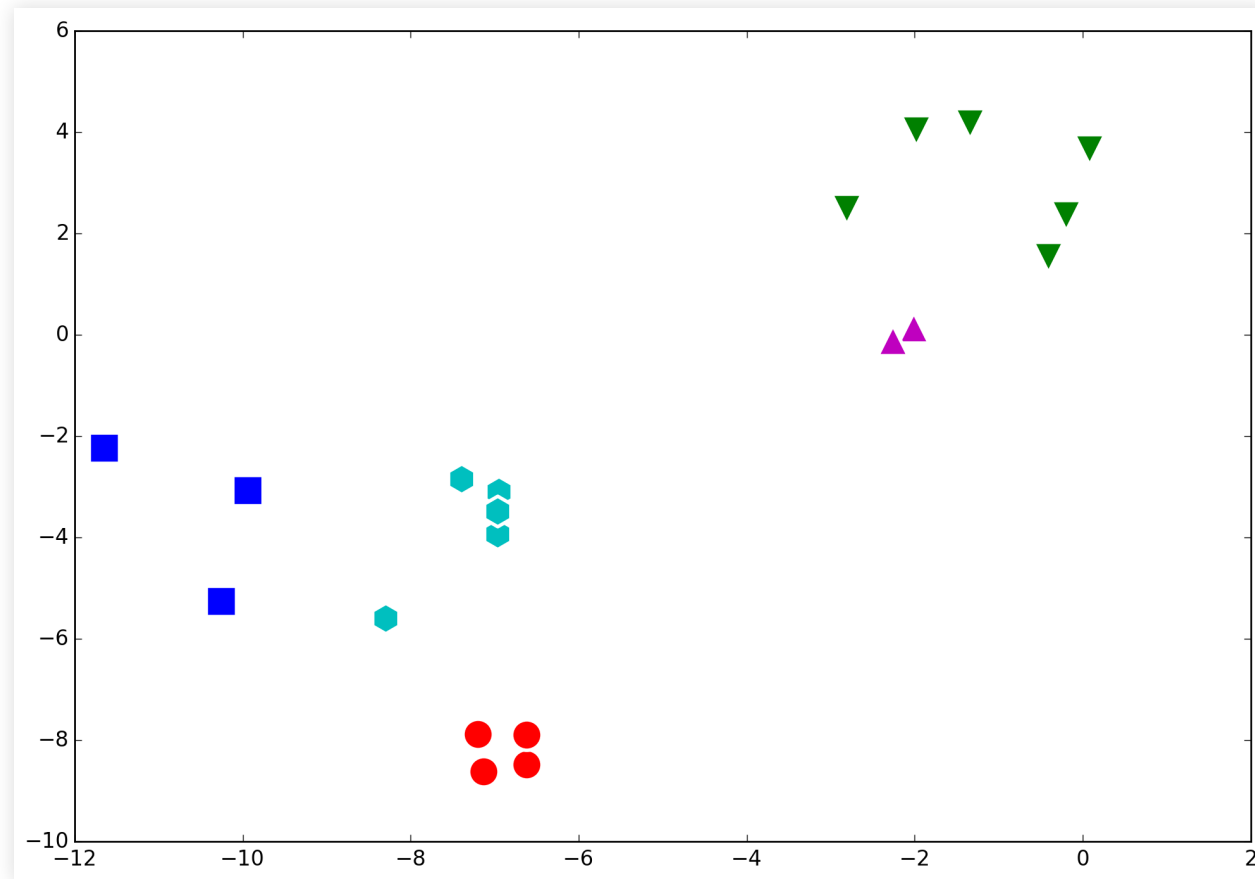
# Defining clusters

## How do we define our clusters?

- Several things we need to decide about the set of clusters
- Partitional clustering:
  - Data is divided into groups at the same level
- Hierarchical clustering:
  - Clusters are nested within larger clusters, in a tree

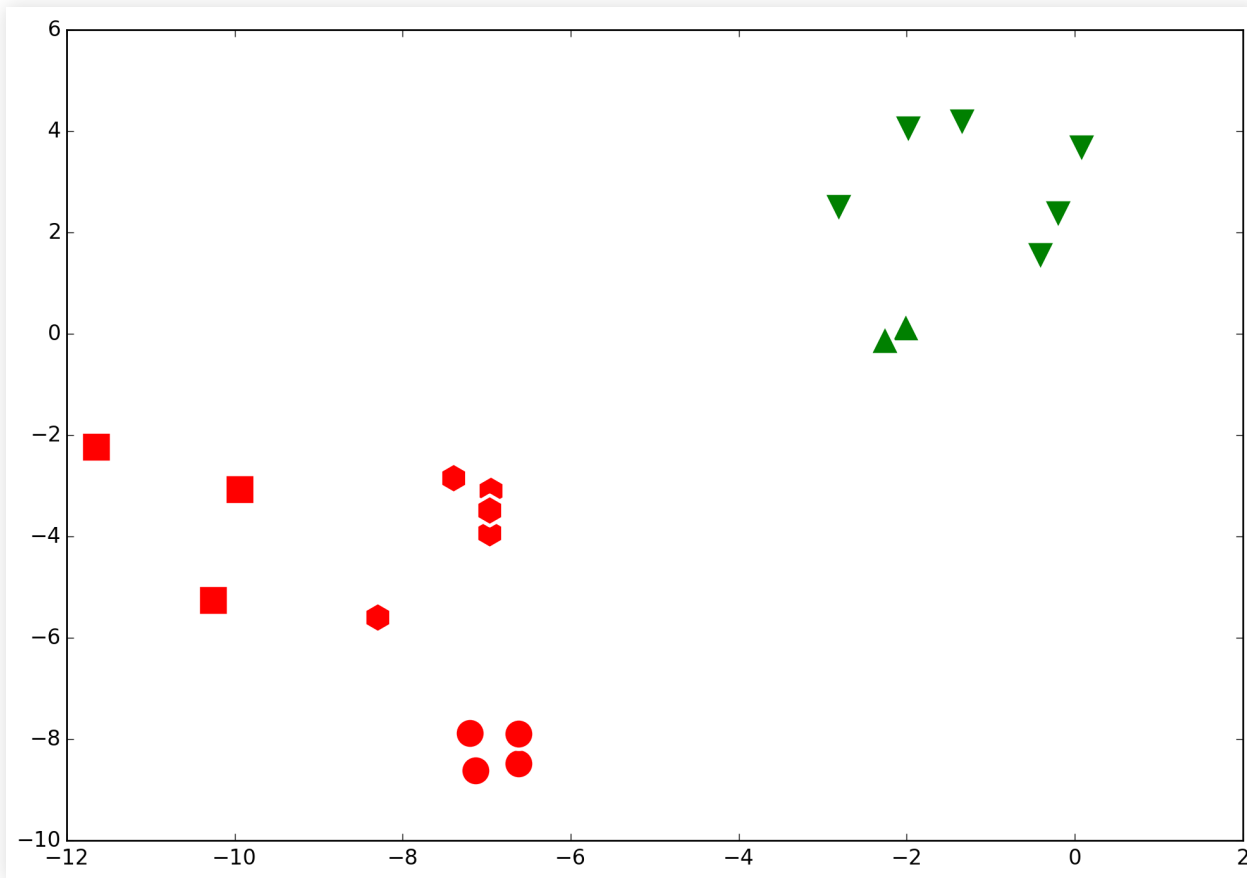
# Defining clusters

## ■ Partitional clustering



# Defining clusters

## ■ Hierarchical clustering



# Defining clusters

## Clustering, example membership

### ■ Exclusive clustering:

- Each example belongs to only one cluster

### ■ Overlapping clustering:

- Examples may belong to more than one cluster

### ■ Fuzzy clustering:

- Each example belongs to clusters with  $w_k \in [0; 1]$

### ■ Probabilistic clustering:

- As fuzzy, but  $\sum_{k=1}^K w_k = 1$

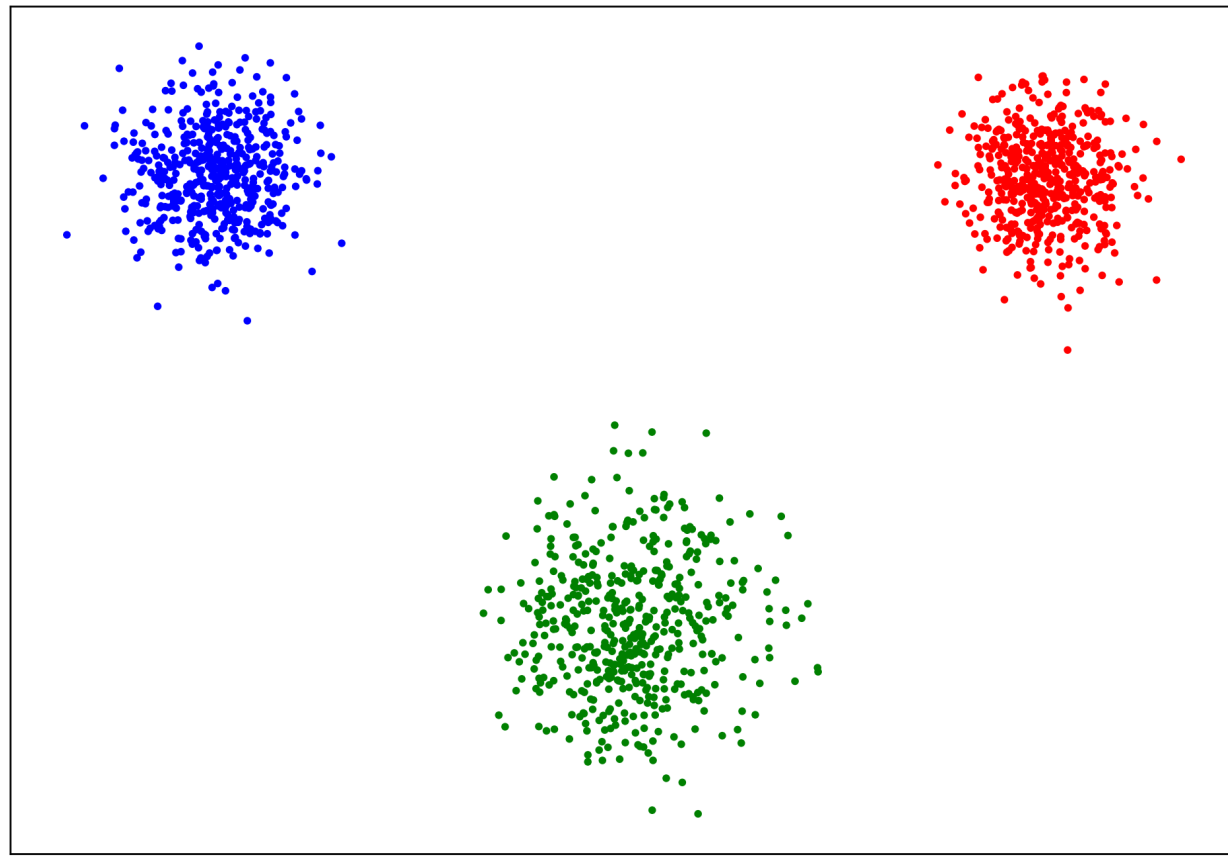
## Clustering, coverage of examples

- Complete clustering:
  - All examples are assigned to cluster (or clusters)
- Partial clustering:
  - Some examples unassigned (e.g. noise, irrelevant data, etc)



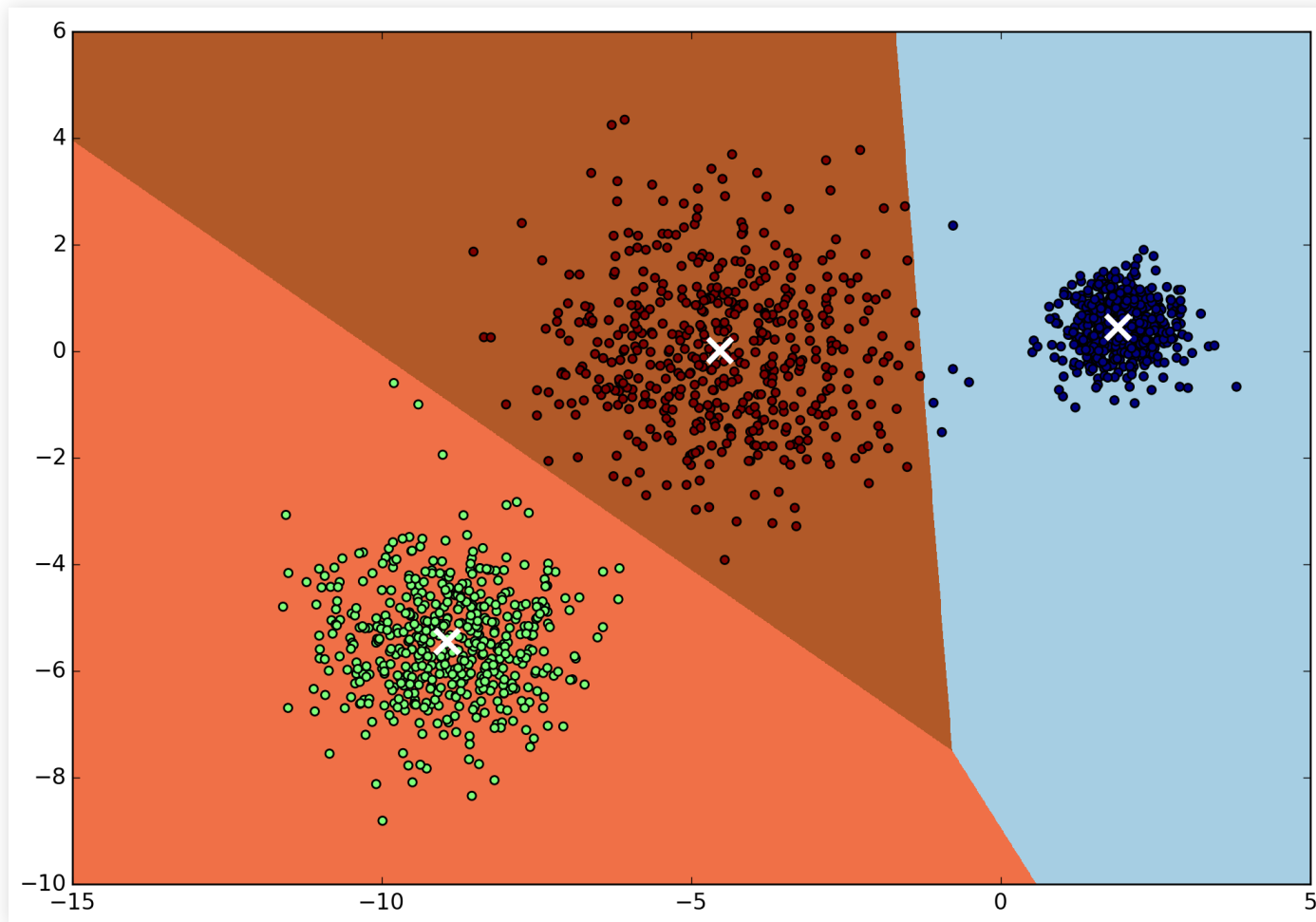
# Types of clusters

- Well-Separated (data dependent): More similar to all cluster than other clusters



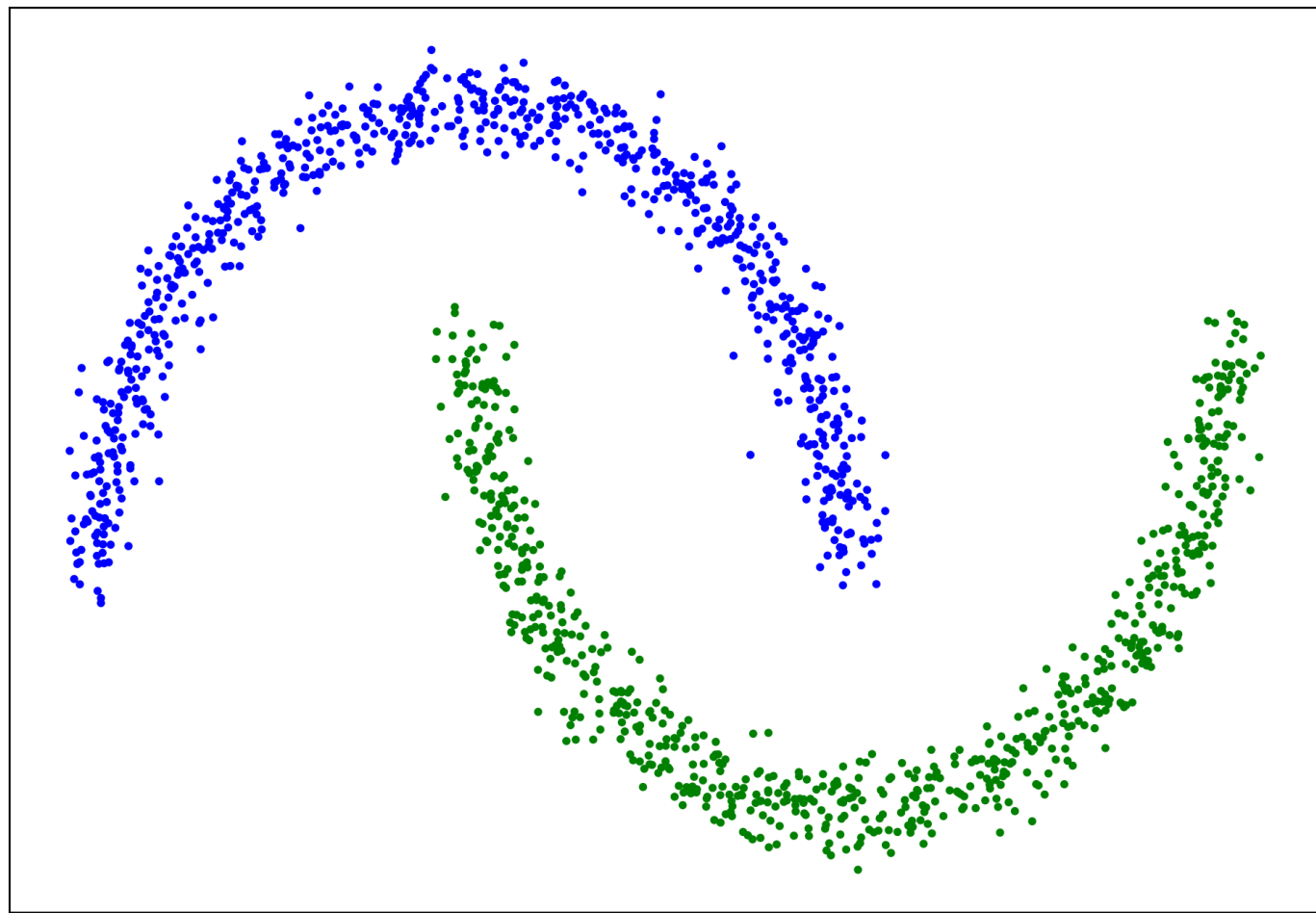
# Types of clusters

- Prototype-based clustering: Examples closer to prototype



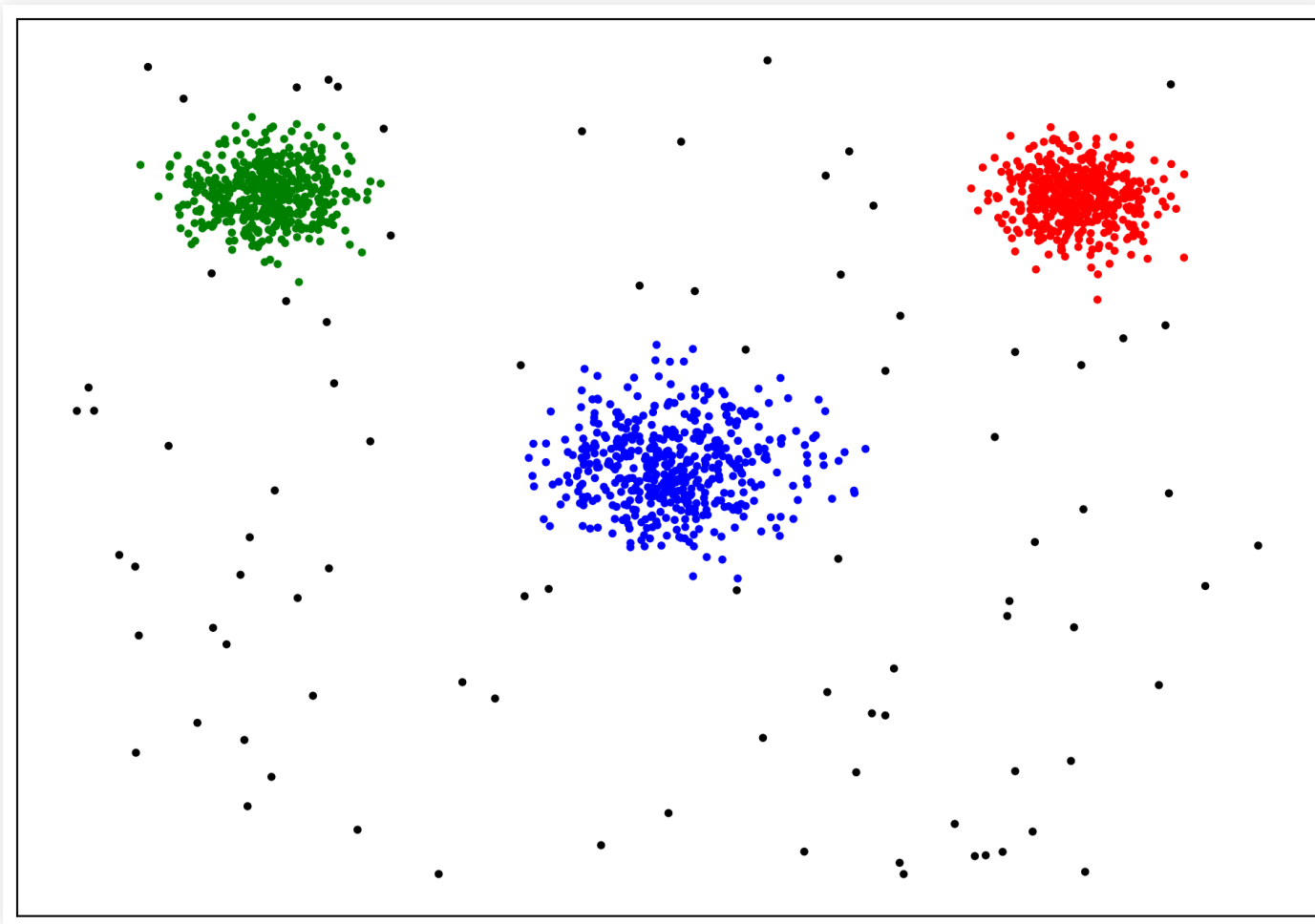
# Types of clusters

- Contiguity-based clustering: Closer in cluster than outside



# Types of clusters

- Density-based clustering: High density regions (discards noise)



# Clustering

- How do we compare examples?
  - (What similarity measures?)
- How are examples related to clusters?
  - (All in clusters? Some? Partially or fully?)
- How do we group examples together?
  - (Prototypes? Density? Affinity?)
- How meaningful are the clusters?
  - (Statistically significant? Make sense?)

**The goal: making data more intelligible**

## Clustering vs Classification

- In classification we have a clear goal:
  - Predict the labels given by the data
  - We can measure error (supervised learning)
- In clustering the goal is not defined a priori:
  - Why do we want to cluster?
  - Simplify, find meaningful groups, understand patterns?
  - How do we want to cluster?
- In clustering the categories are given by the model and not the data.
  - It's like classification but the we invent the classes...

## K-MEANS

## Find best clustering of $k$ clusters

- Define clusters by proximity to the mean of the cluster
- The number of centroids and clusters is predefined ( $k$ )
- Partitional, exclusive, complete and prototype-based

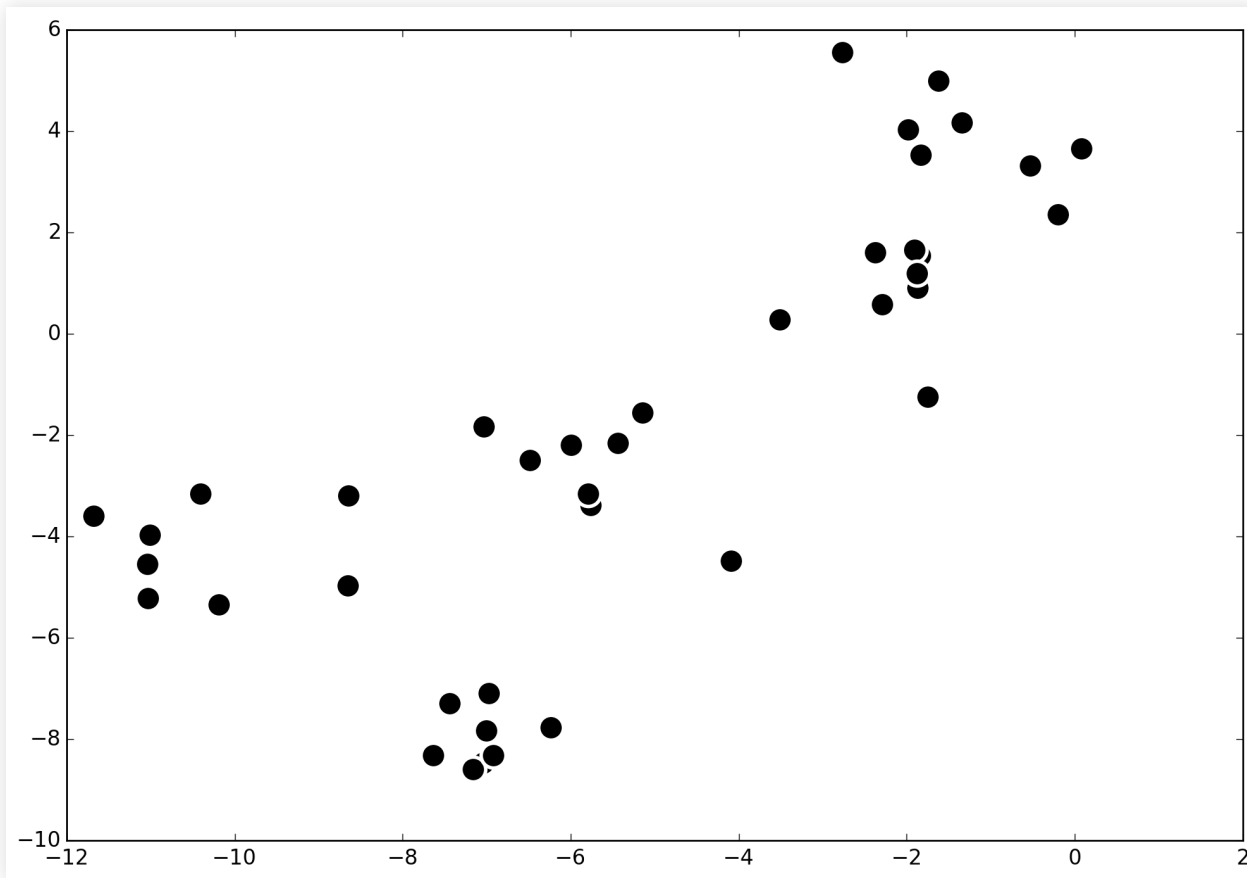
## K-means (Lloyd's) algorithm

- Start with random centroids
- Assign each example to closest centroid
- Update centroids to mean of respective cluster
- Recompute clusters, repeat until convergence



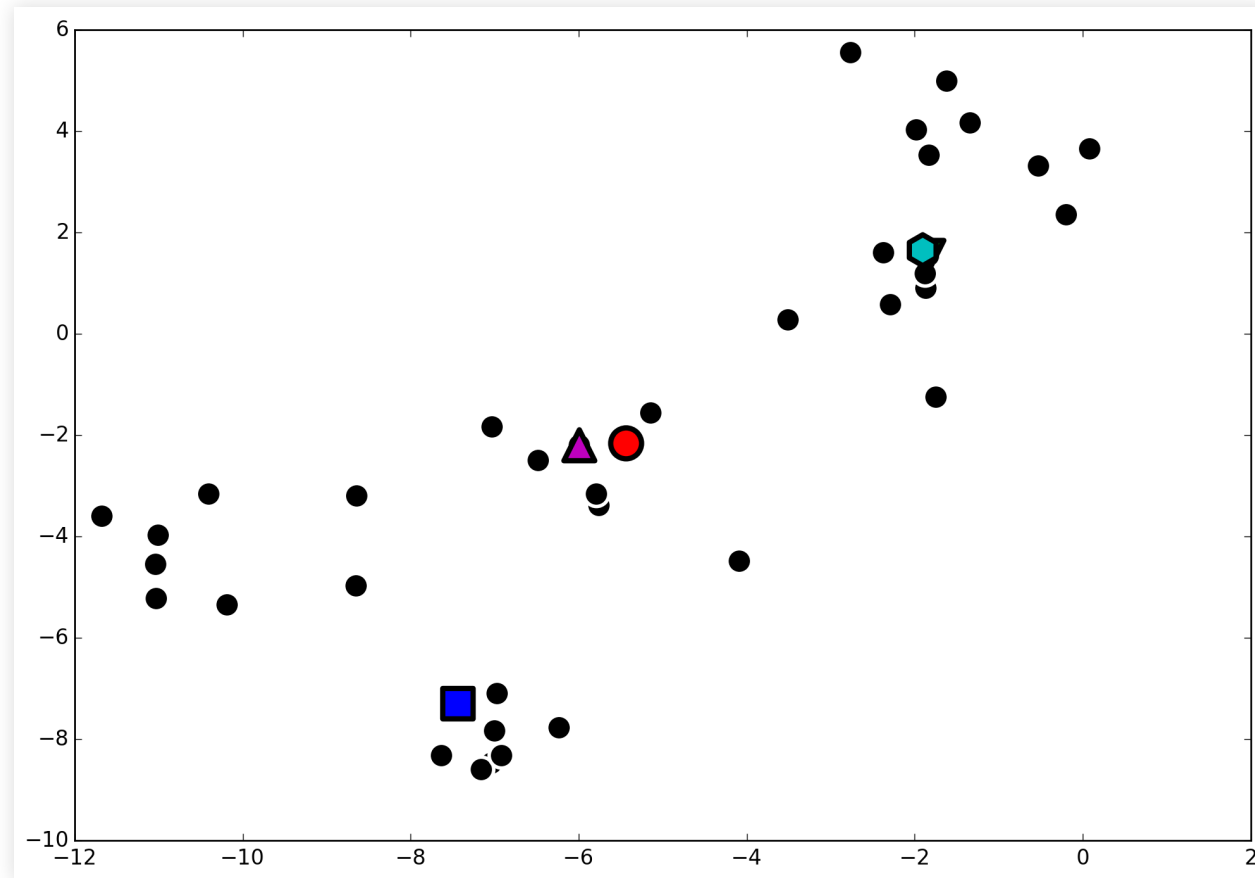
# K-means initialization

- Forgy : start with coordinates of a random set of examples



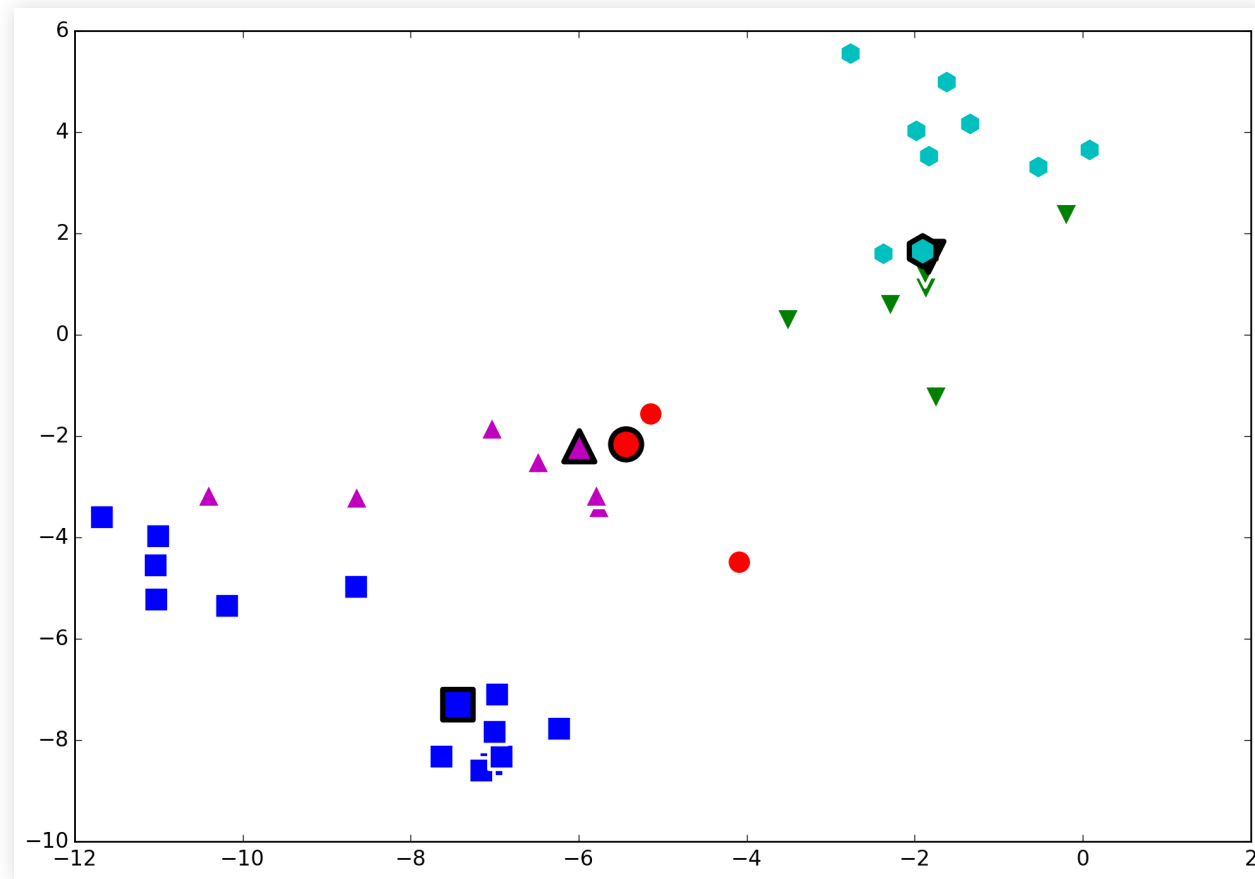
# K-means initialization

- Forgy : start with coordinates of a random set of examples



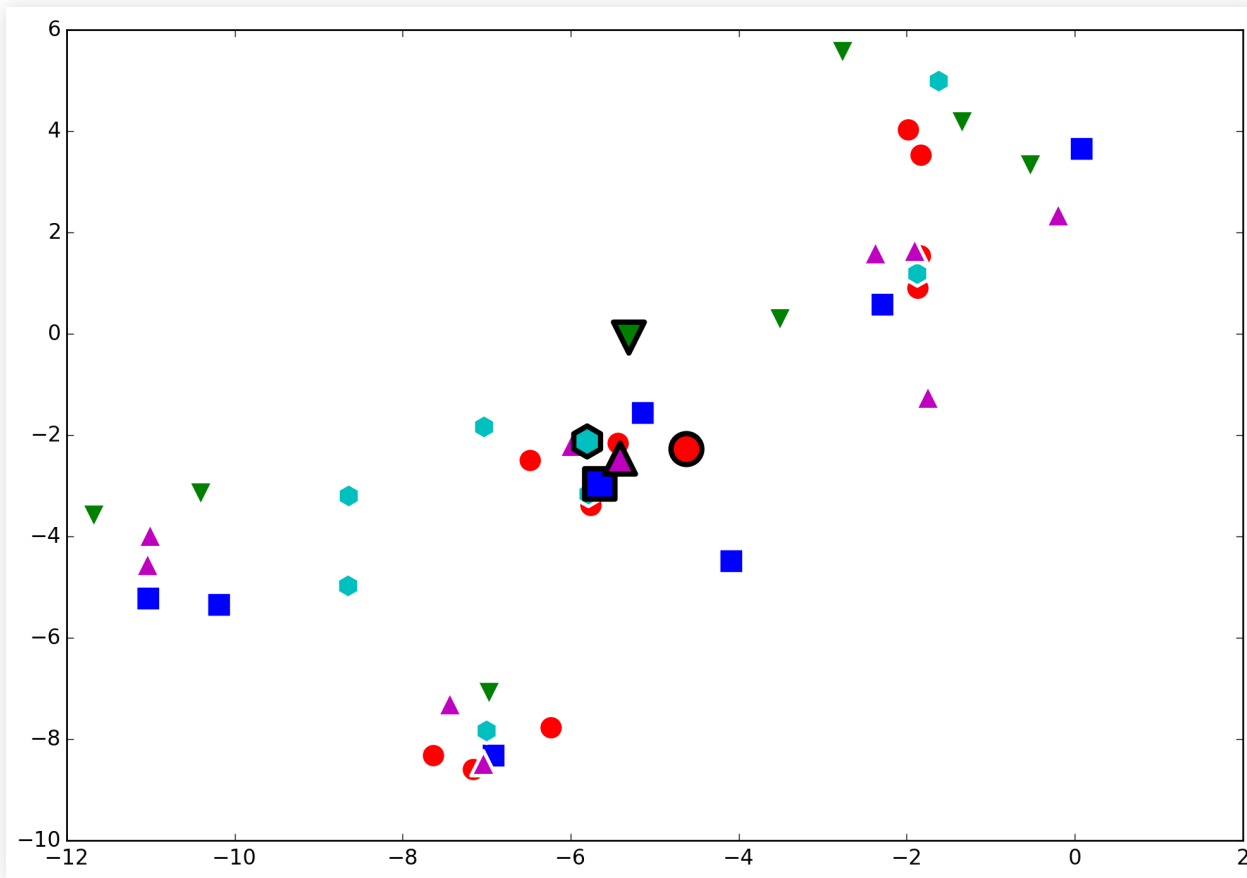
# K-means initialization

- Forgy : assign each point to closest centroid



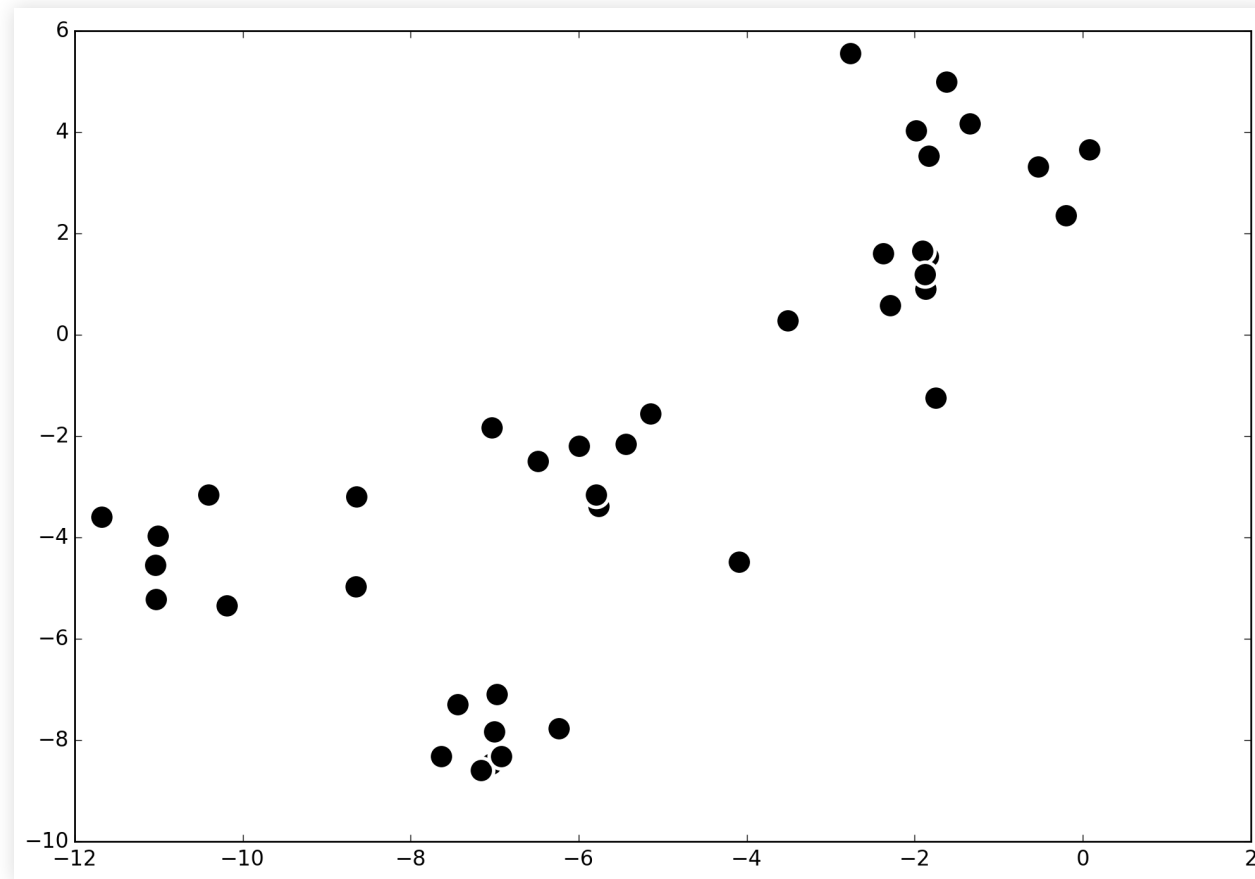
# K-means initialization

- Random Partition : random assignment, compute means



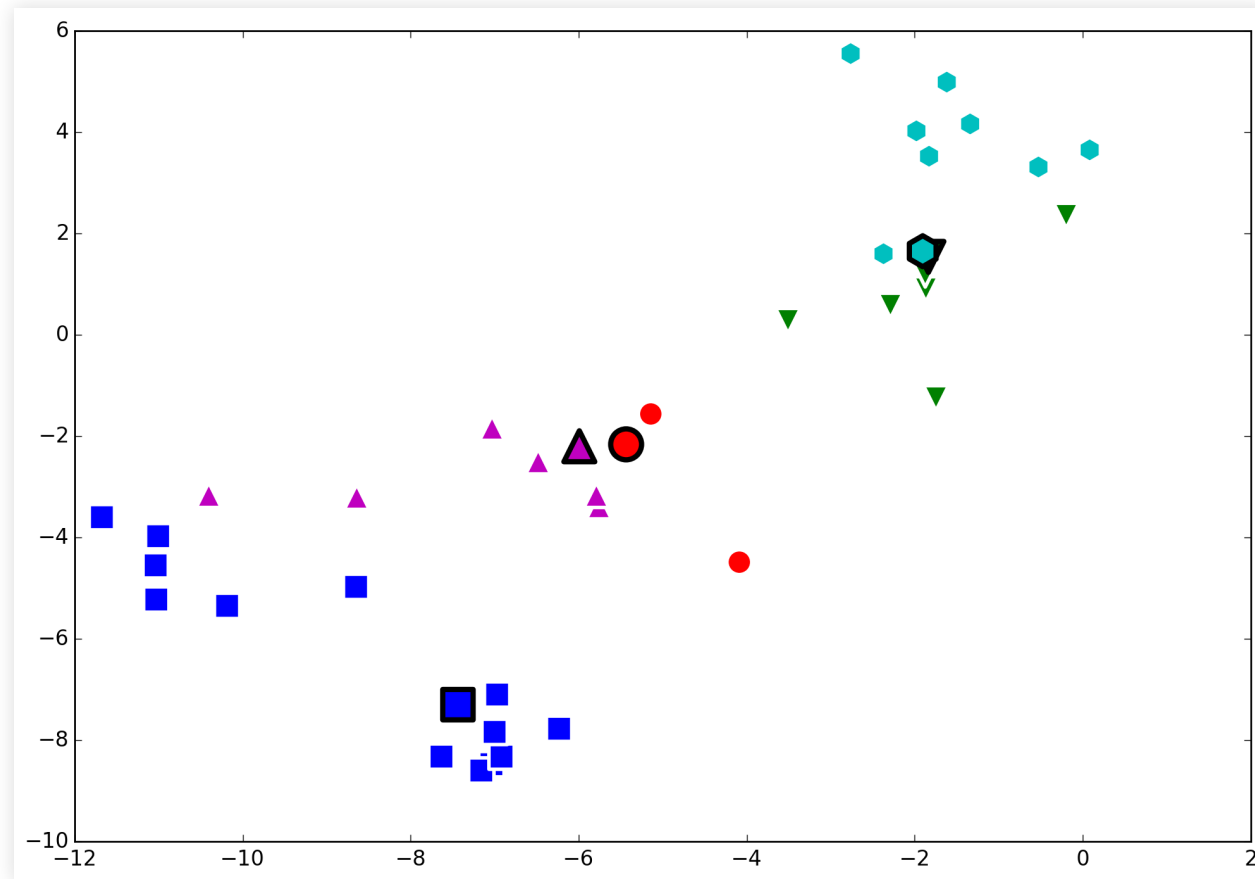
# K-means algorithm

## ■ Original data:



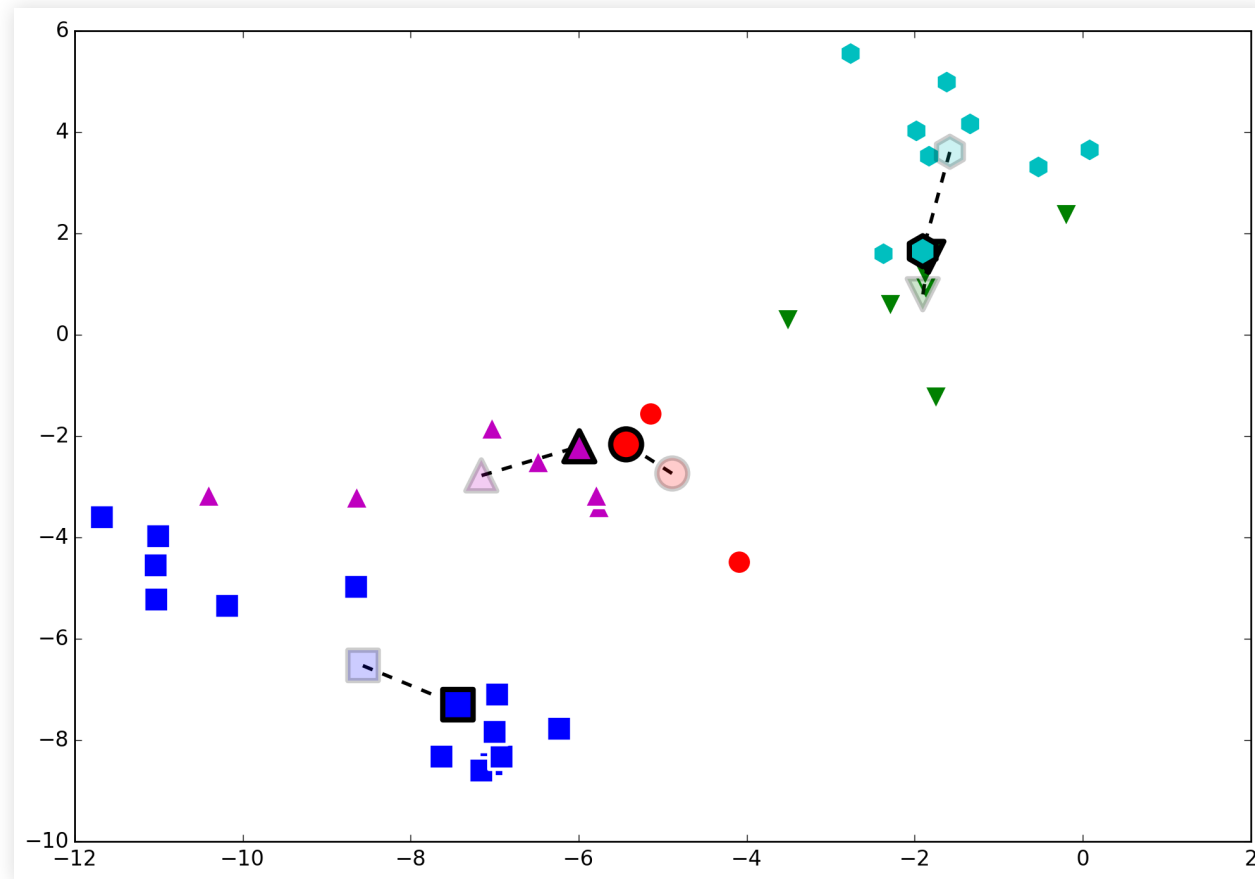
# K-means algorithm

- Initialize (Forgy), compute clusters



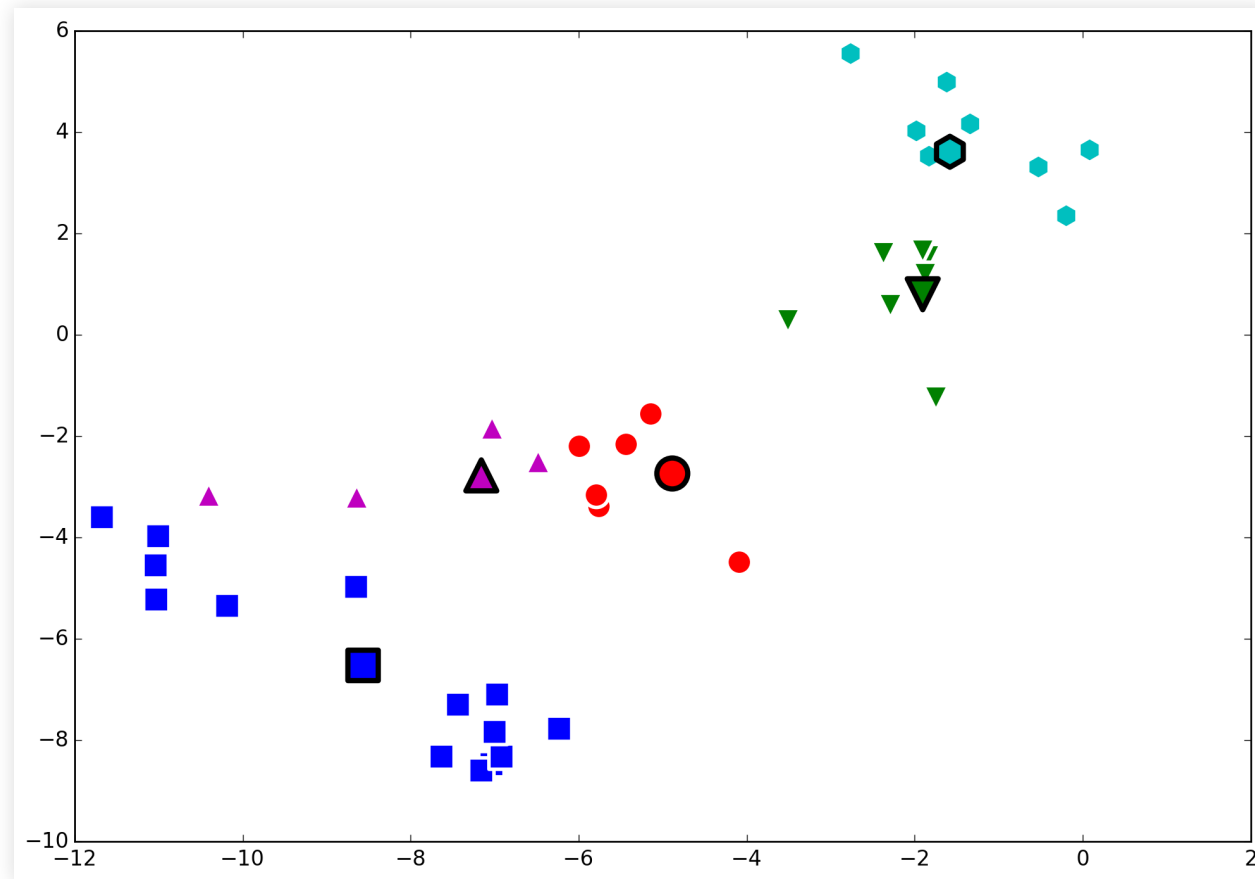
# K-means algorithm

- Compute new means, update centroids



# K-means algorithm

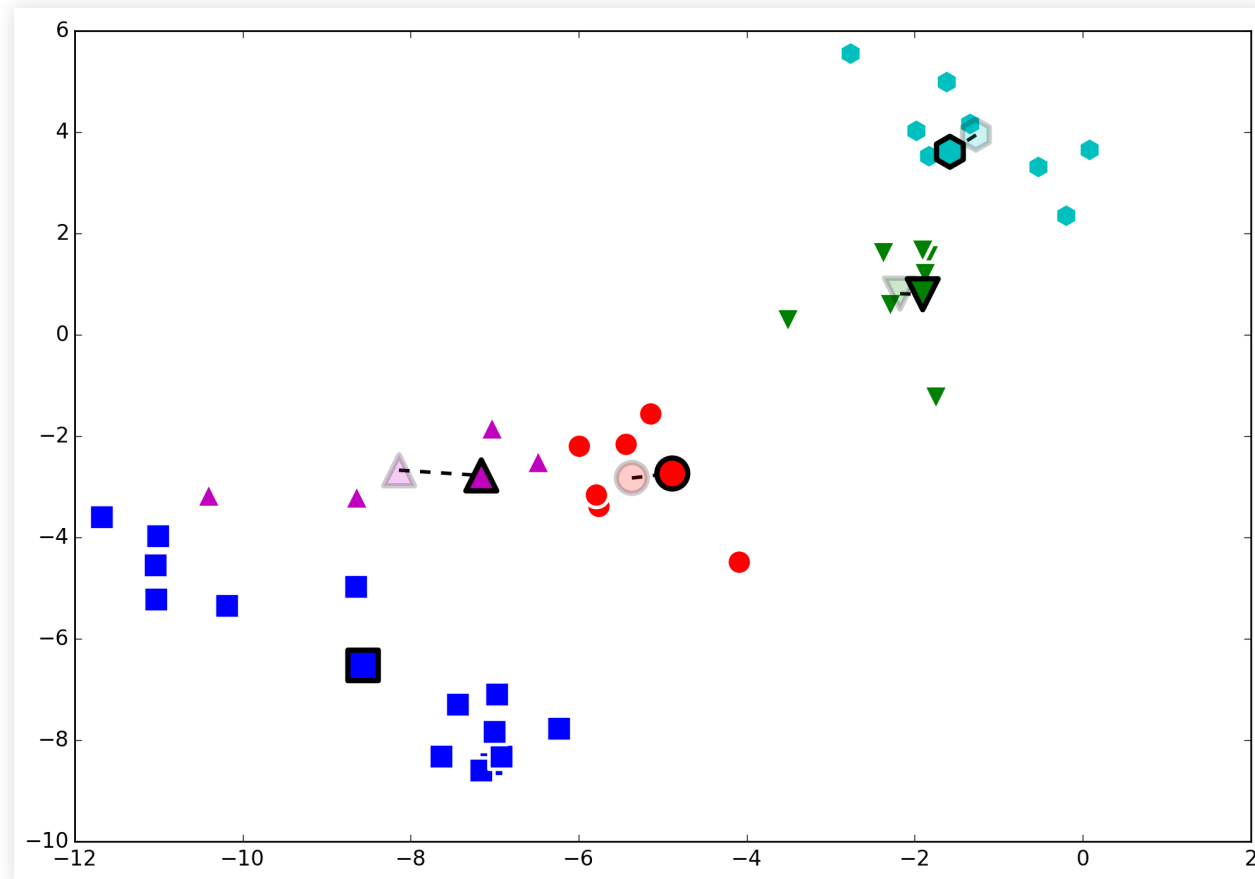
## ■ Recompute clusters





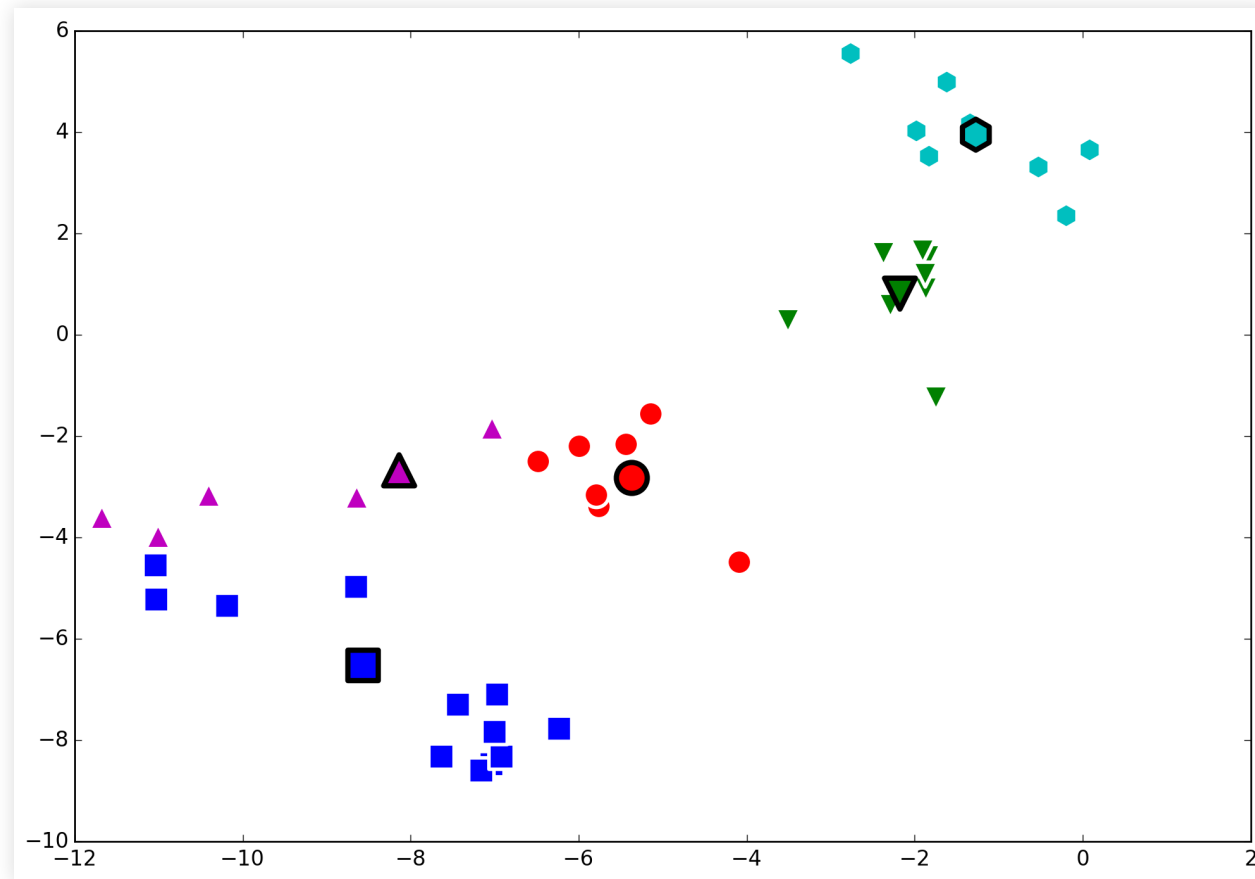
# K-means algorithm

- Compute new means, update centroids



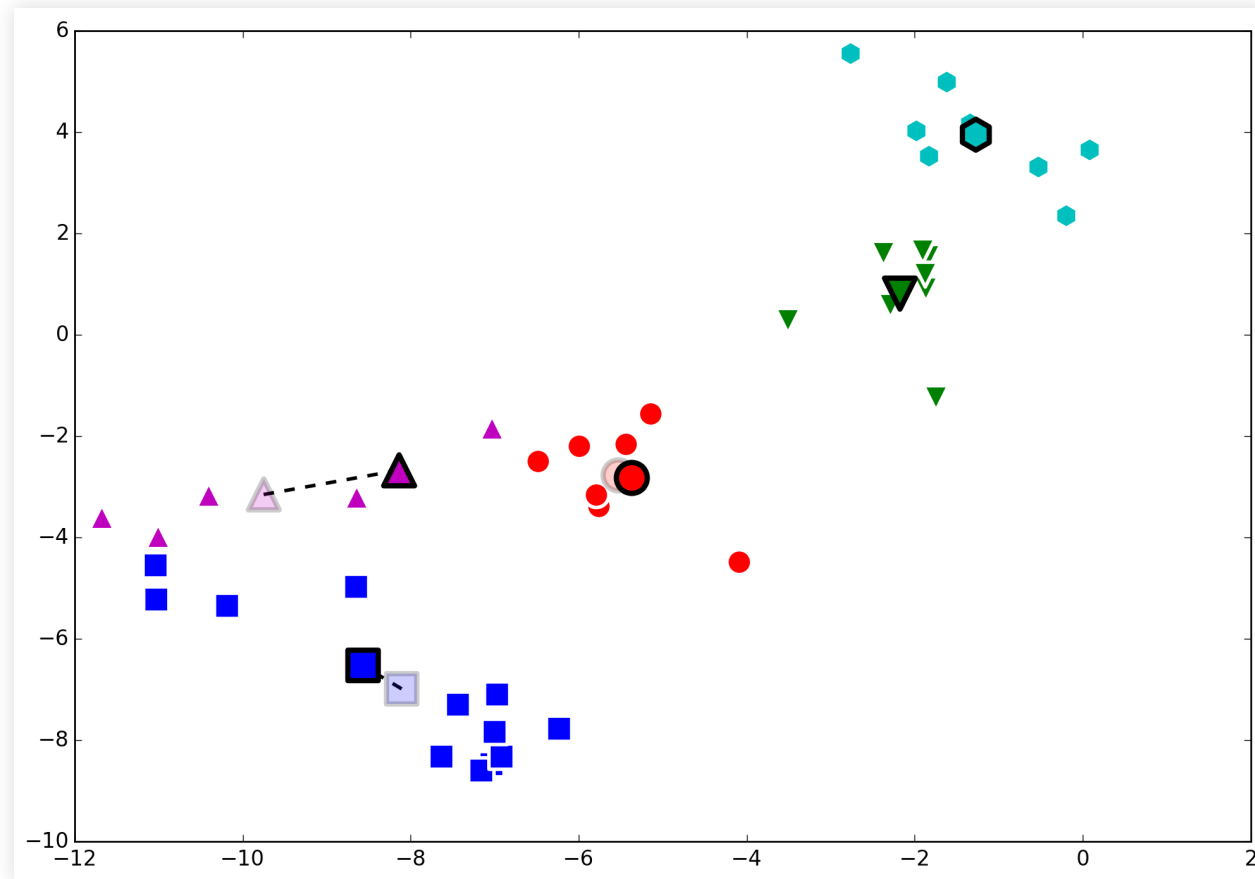
# K-means algorithm

## ■ Recompute clusters



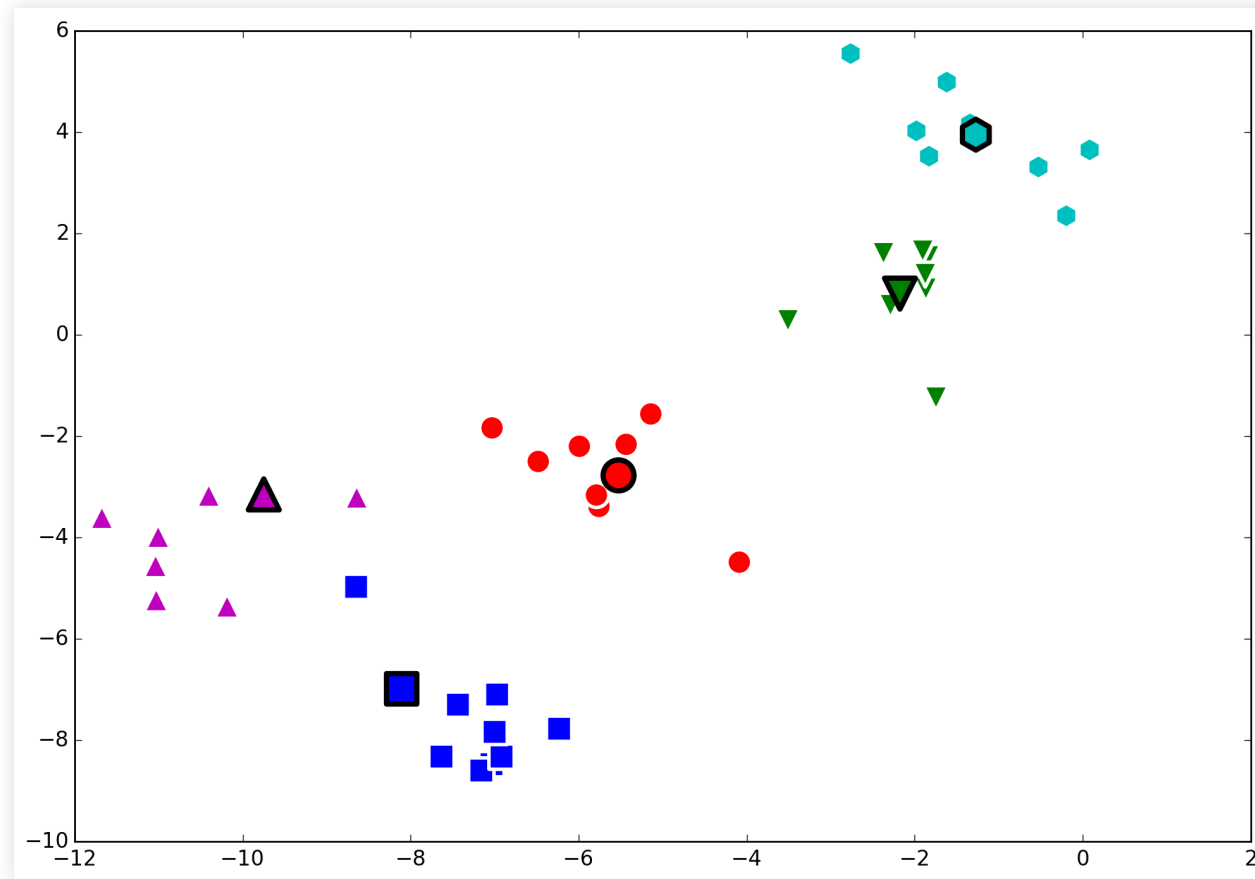
# K-means algorithm

- Compute new means, update centroids



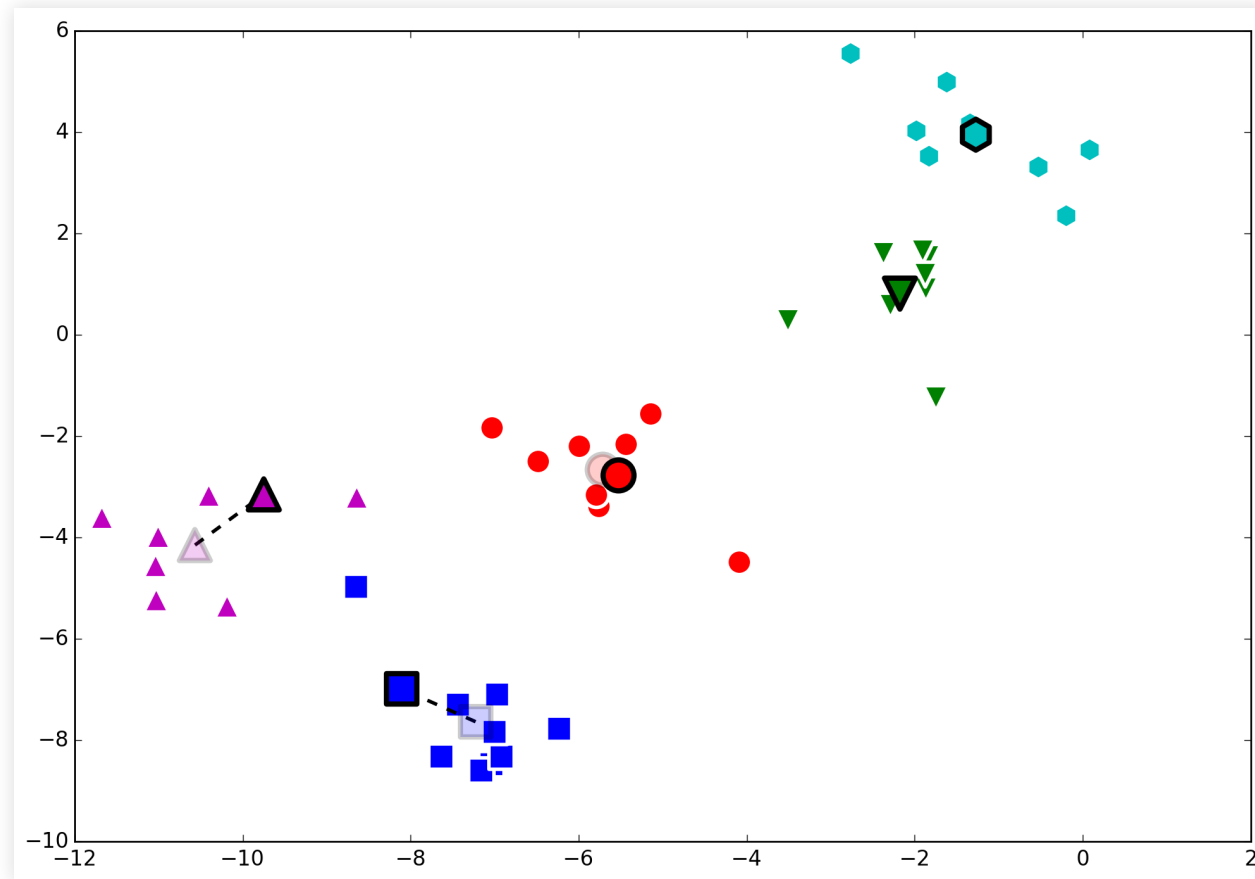
# K-means algorithm

## ■ Recompute clusters



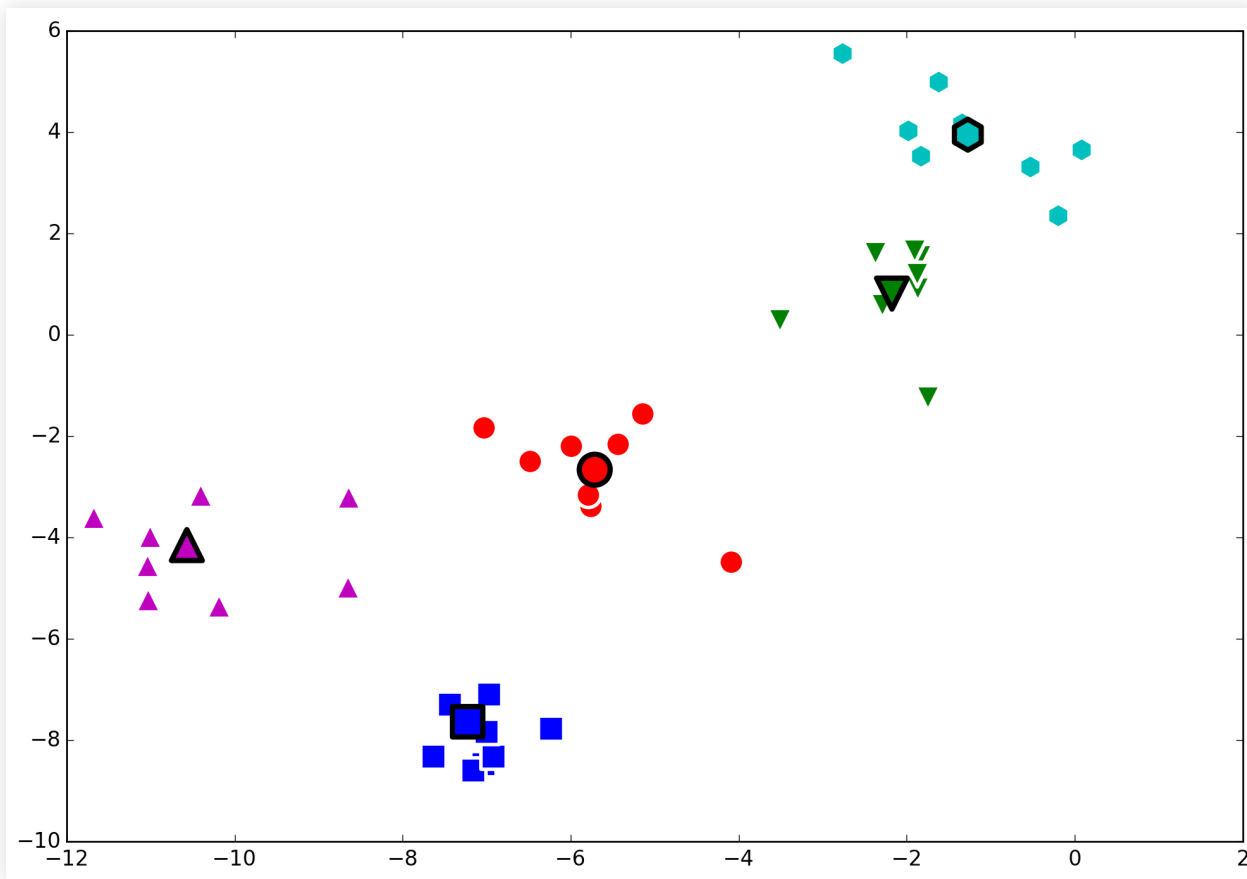
# K-means algorithm

- Compute new means, update centroids



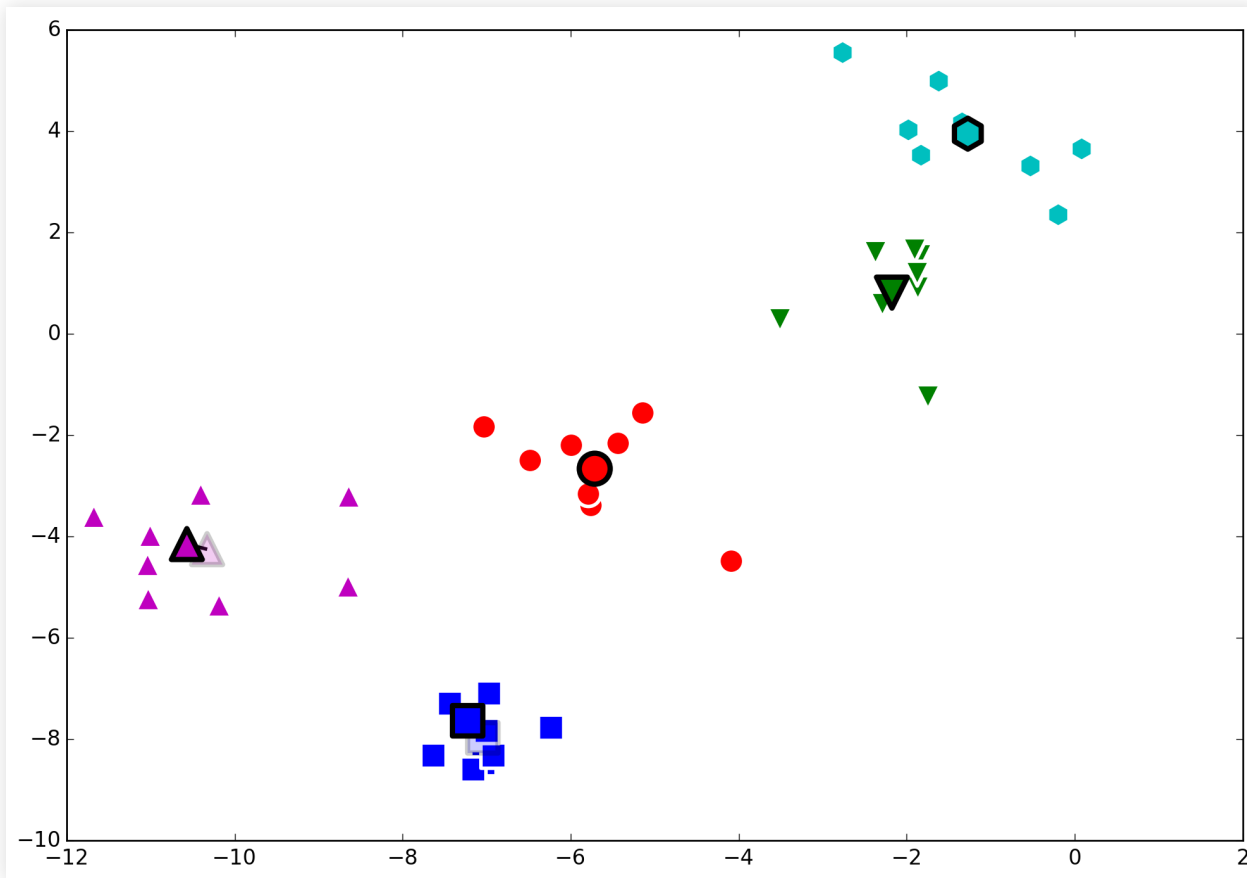
# K-means algorithm

## ■ Recompute clusters



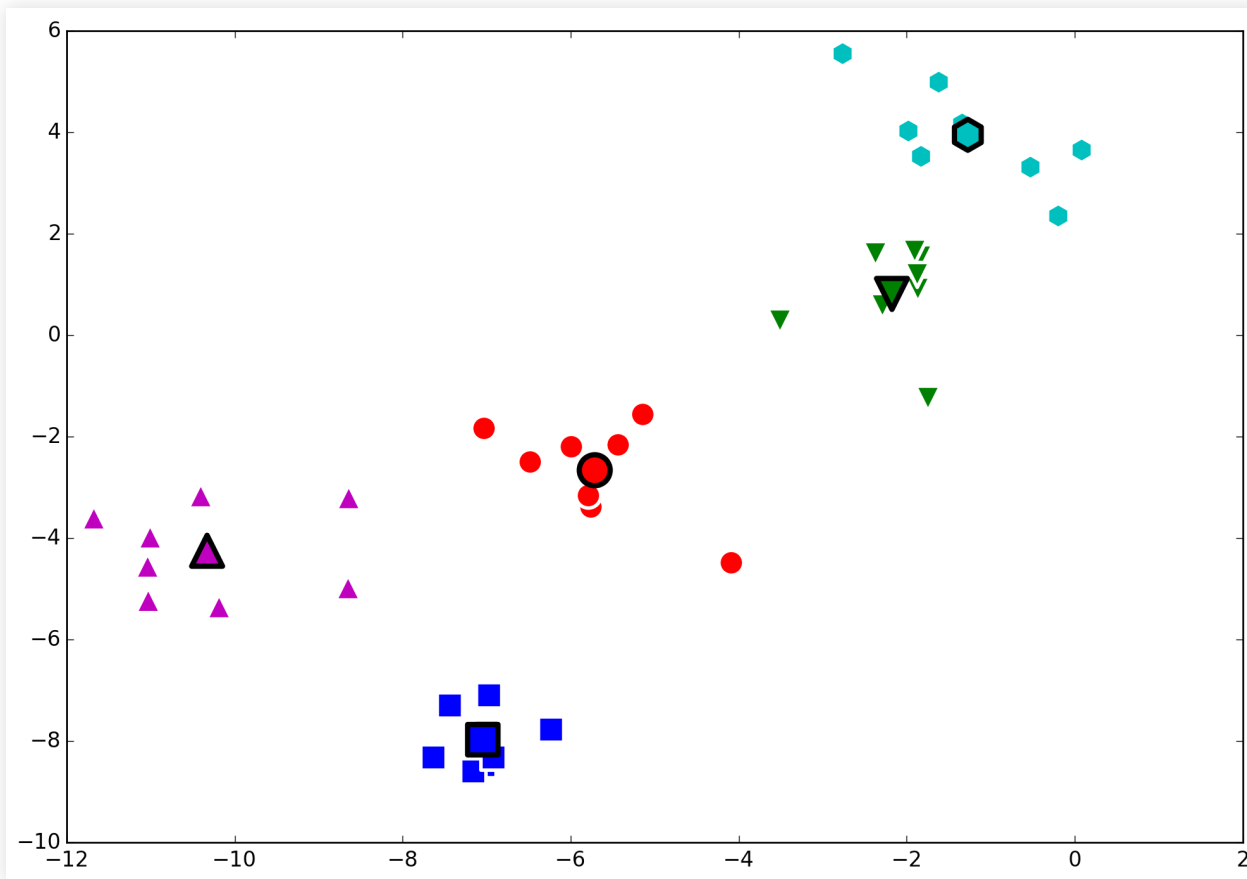
# K-means algorithm

- Compute new means, update centroids



# K-means algorithm

## ■ Until convergence





# K-means algorithm

## ■ Attribute points to centroids

```
def closest_centroids(data, centroids):  
    ys = np.zeros(data.shape[0])  
    for ix in range(data.shape[0]):  
        dists = np.sum((centroids-data[ix, :])**2, axis=1)  
        ys[ix] = np.argmin(dists)  
    return ys
```

## ■ Move centroids to mean points

```
def adjust_centroids(data, centroids):  
    ys = closest_centroids(data, centroids)  
    for ix in range(centroids.shape[0]):  
        centroids[ix, :] = np.mean(data[ys==ix, :], axis=0)
```

# K-means algorithm

## ■ Initialization (Forgy method)

```
def forgy(data,k):  
    ix = np.arange(data.shape[0])  
    np.random.shuffle(ix)  
    return data[ix[:k],:].copy()
```

## ■ Initialization (Random Partition)

```
def rand_part(data,k):  
    ys = np.random.randint(0,k,data.shape[0])  
    centroids = np.zeros((k,data.shape[1]))  
    for ix in range(k):  
        centroids[ix,:] = np.mean(data[ys==ix,:],axis=0)  
    return centroids,ys
```

# K-means algorithm

- Finding the best prototypes for the clusters
- Distance measure, typically euclidean, but Minkowsky more general:

$$D_{x,x'} = \sqrt[p]{\sum_d |x_d - x'_d|^p}$$

- Conceptually similar to a SOM (without the topology)

## K-medoids

- Variant of k-means where prototypes are data points (medoids)
- Needs only a dissimilarity matrix
- Assign each example to cluster of most similar medoid
- For each medoid and example, test if example is better medoid
- Stop when no improvement possible

## EM algorithm

# Expectation-Maximization algorithm

## Background

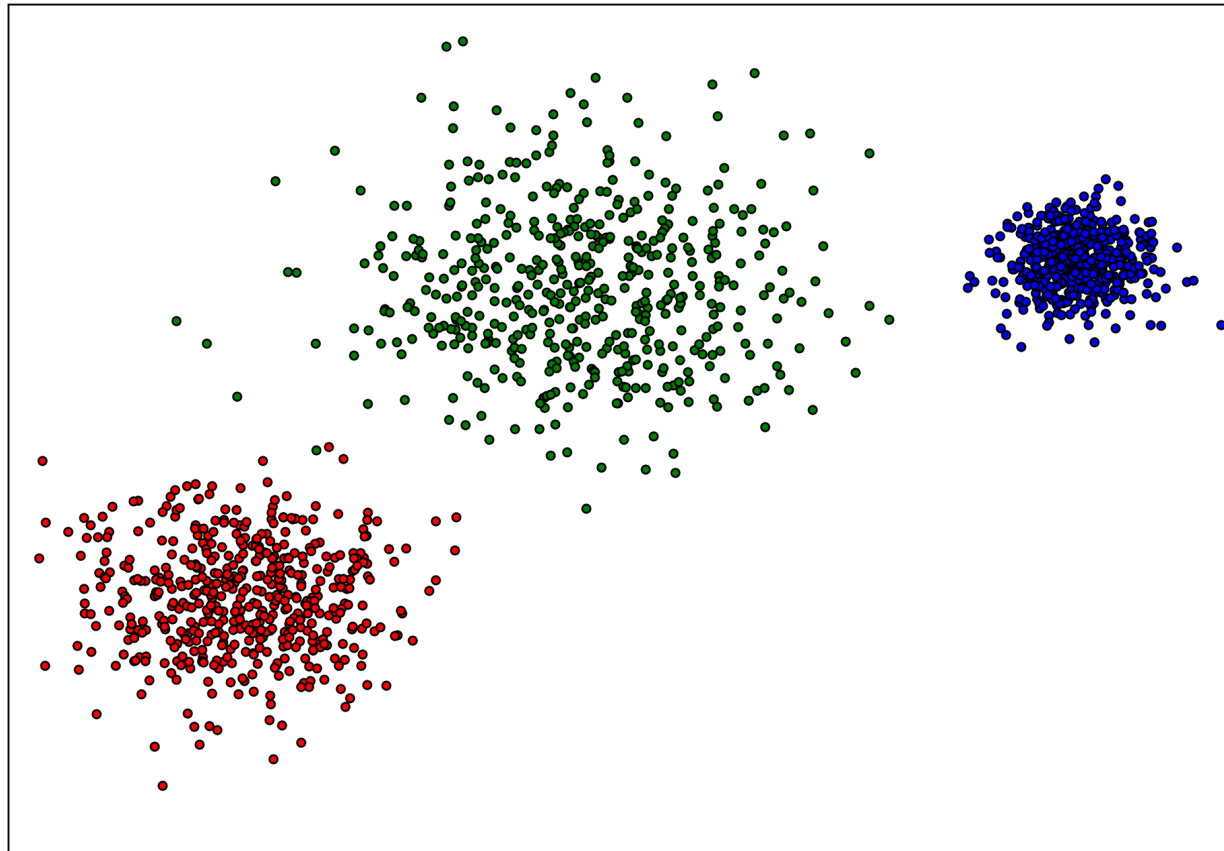
- Set  $X$  of observed data
- Set  $Z$  of missing data or latent variables
- Unknown parameters  $\theta$
- Likelihood function  $L(\theta; X, Z) = p(X, Z|\theta)$

## Contrast with supervised learning:

- In classification classes are determined by observation
  - Classes are labels in the training set
- In clustering, "classes" are latent variables in the model
  - Clustering is like classification but with unspecified classes
  - The algorithm will discover (invent?) the "classes"

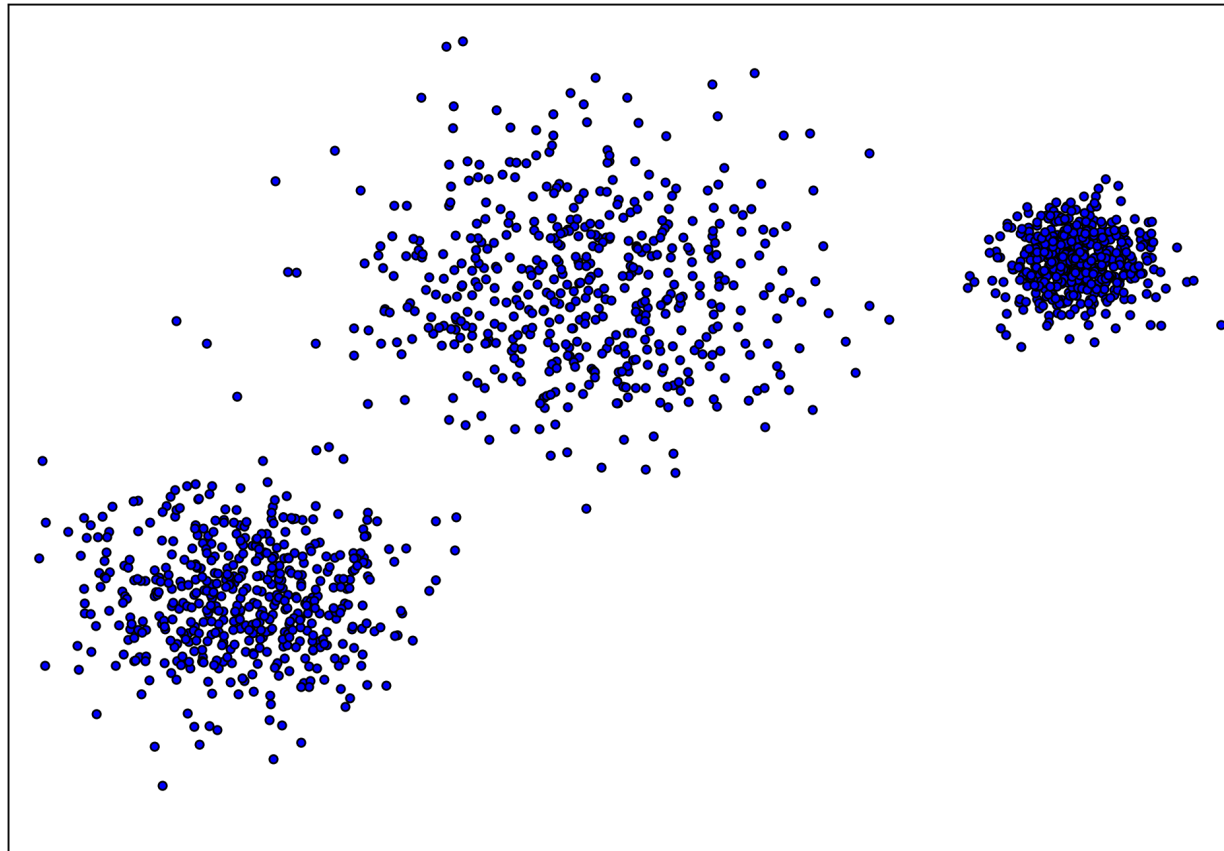
# Expectation-Maximization algorithm

- Example:  $\{X, Z\}$  is the complete data



# Expectation-Maximization algorithm

- But we only have  $X$ , the incomplete data



# Expectation-Maximization algorithm

- We cannot compute  $L(\theta; X, Z) = p(X, Z|\theta)$  directly
  - Because  $Z$  is unknown
- But we can estimate the posterior probability  $p(Z|X, \theta^{old})$

## EM algorithm

- Expectation step: compute the expected values of  $Z$  to get a likelihood function:

$$Q(\theta, \theta^{old}) = E_{Z|X, \theta^{old}} \ln p(X, Z|\theta)$$

- Maximization step: obtain  $\theta^{new}$  maximizing  $Q(\theta, \theta^{old})$

$$\theta^{new} = \arg \max_{\theta} E_{Z|X, \theta^{old}} \ln p(X, Z|\theta)$$

- Repeat  $\theta^{old} \leftarrow \theta^{new}$  until convergence



# Expectation-Maximization algorithm

## EM and k-means

- We can see the EM idea in K-Means as an alternating optimization over different variables
- Define this distortion measure (objective function):

$$J = \sum_{n=1}^N \sum_{k=1}^K r_{nk} \|x_n - \mu_k\|^2$$

- Where  $r_{nk}$  is 1 if  $x_n$  belongs to  $\mu_k$ , else 0
- We minimize first w.r.t.  $r_{nk}$  by assigning each example to the closest centroid
- Then we minimize w.r.t. each  $\mu_k$  by setting the derivative to zero:

$$2 \sum_{k=1}^K r_{nk} (x_n - \mu_k) = 0 \iff \mu_k = \frac{\sum r_{nk} x_n}{\sum r_{nk}}$$

# Expectation-Maximization algorithm

## EM and k-means

- EM is (almost) the algorithm used for k-means
  - Estimate  $r_{nk}$ , cluster assignment, from current centroids
  - Estimation of the likelihood function (in this case, quadratic distance w.r.t.  $\mu_k$ )
  - Means maximize the estimated likelihood function (minimize distance)
  - (We'll see this better after gaussian mixtures)

## K-means Example

# K-means color quantization

- Vector quantization is a common technique in signal compression
- We'll use k-means to quantize the color values of an image to reduce the color space
- Example image from Wikipedia
- Demo based on Scikit-learn demo on color quantization

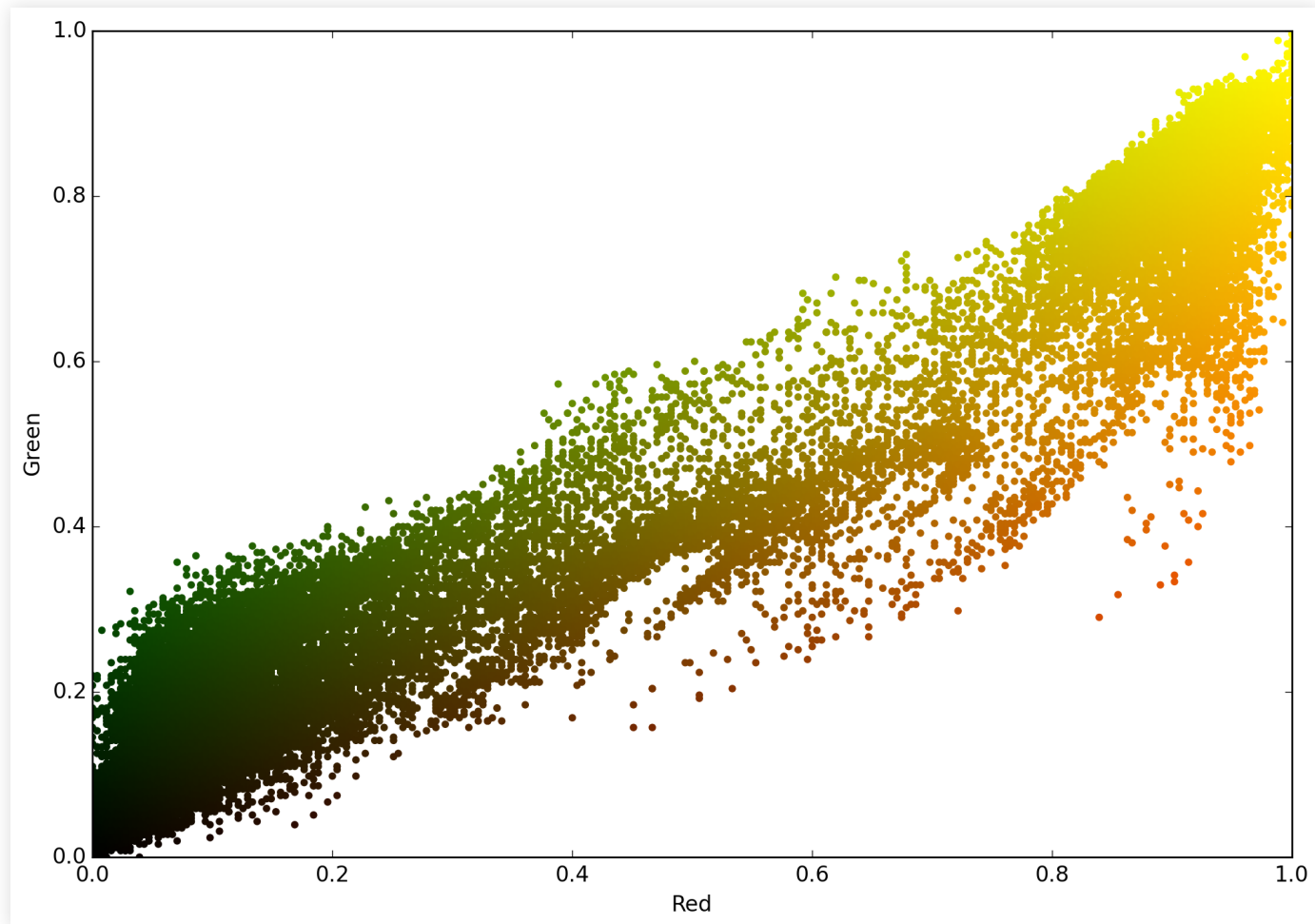
# K-means color quantization

- This image has only red and green (no blue)



# K-means color quantization

- So we can plot all pixels green vs red



# K-means color quantization

- Load and create pixel array (red, green)

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.cluster import KMeans
from skimage.io import imsave, imread

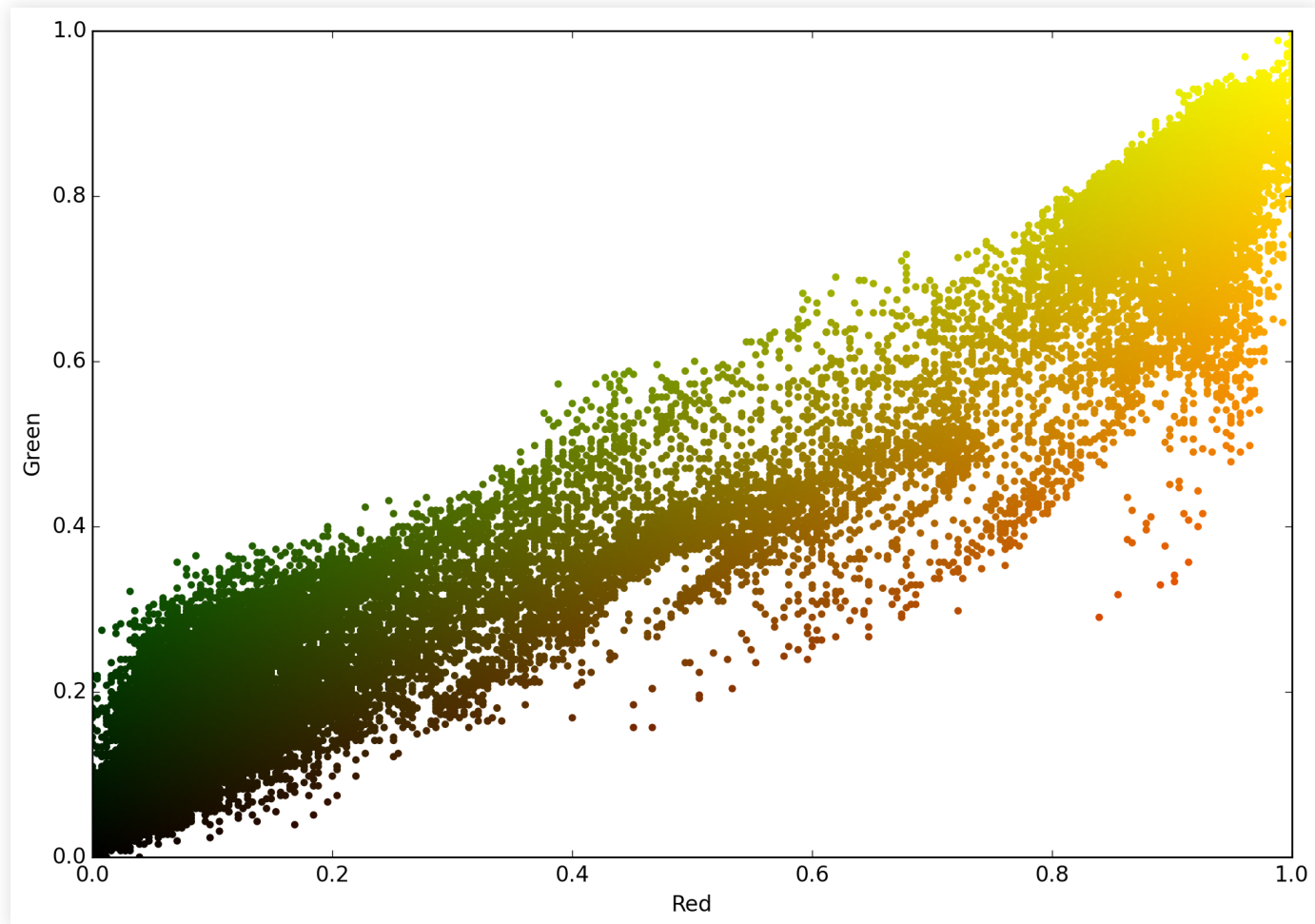
rosa = imread("Rosa.png")
w,h,d = rosa.shape
cols = np.reshape(rosa/255.0, (w * h, d))
image_array = cols[:, :2]
```

- Plot the pixel colors(red, green)

```
plt.figure(figsize=(12,8))
plt.xlabel('Red')
plt.ylabel('Green')
plt.scatter(image_array[:, 0], image_array[:, 1], color=cols.tolist(), s=10)
plt.axis([0,1,0,1])
plt.savefig('L17-rosa-plot.png', dpi=200, bbox_inches='tight')
```

# K-means color quantization

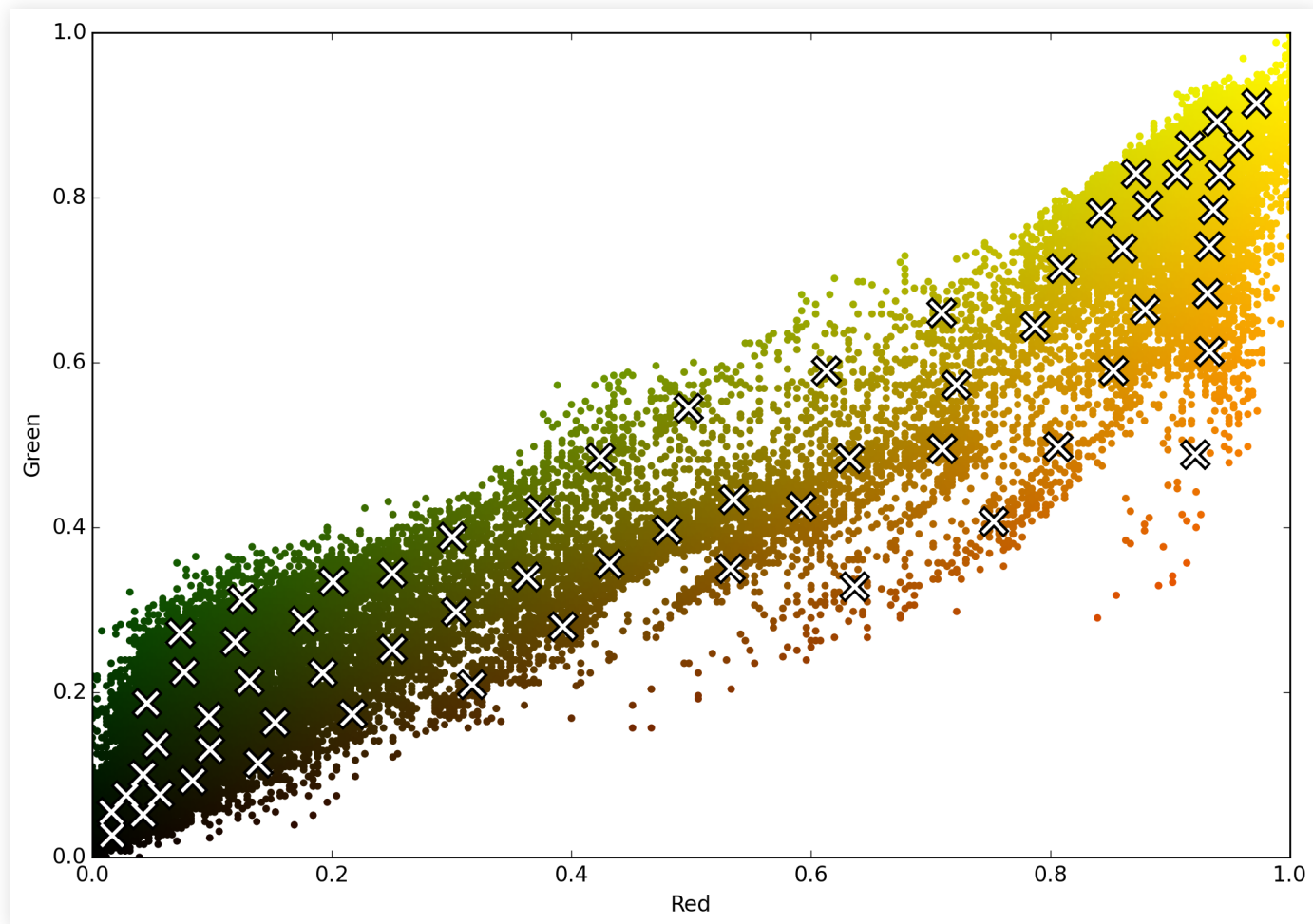
- Plot of all pixels green vs red





# K-means color quantization

- Now we apply k-means with 64 centroids



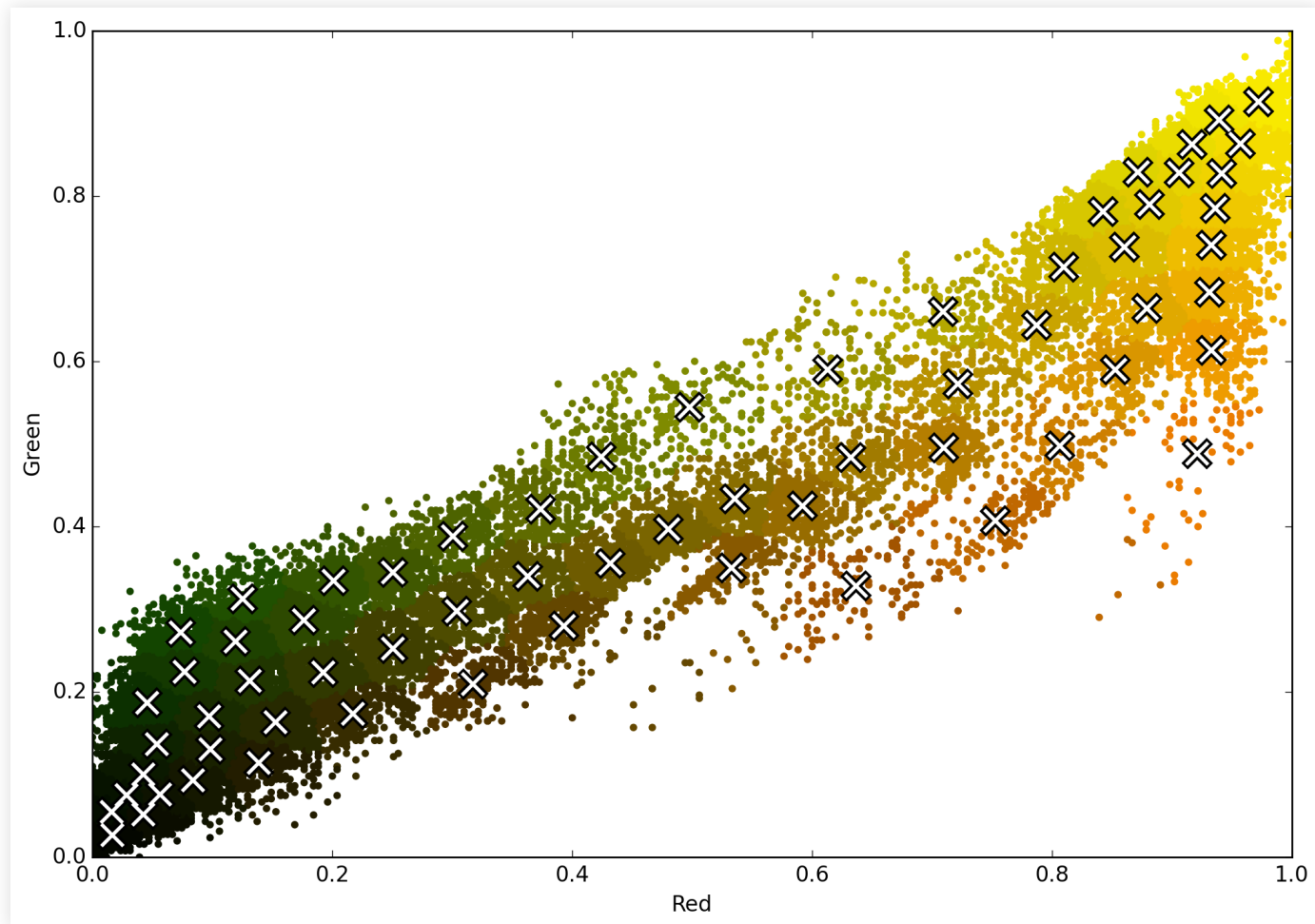
# K-means color quantization

- Compute k-means, with 64 colors (6 bits)

```
n_colors = 64
kmeans = KMeans(n_clusters=n_colors).fit(image_array)
labels = kmeans.predict(image_array)
centroids = kmeans.cluster_centers_
plt.scatter(centroids[:, 0], centroids[:, 1], marker='x',
            color='k', s=200, linewidths=5)
plt.scatter(centroids[:, 0], centroids[:, 1], marker='x',
            color='w', s=150, linewidths=2)
plt.savefig('L17-rosa-plot-cs-'+str(n_colors)+'.png',
            dpi=200, bbox_inches='tight')
```

# K-means color quantization

- And convert pixel colors to centroid



# K-means color quantization

- Convert to centroid color and save

```
c_cols = np.zeros(cols.shape)
for ix in range(cols.shape[0]):
    c_cols[ix,:2]=centroids[labels[ix]]
# ...plot
plt.scatter(image_array[:, 0], image_array[:, 1], color=c_cols.tolist(), s=10)
# ...
imsave('rosa-comp'+str(n_colors)+'.png', np.reshape(c_cols,(w,h,3)))
```

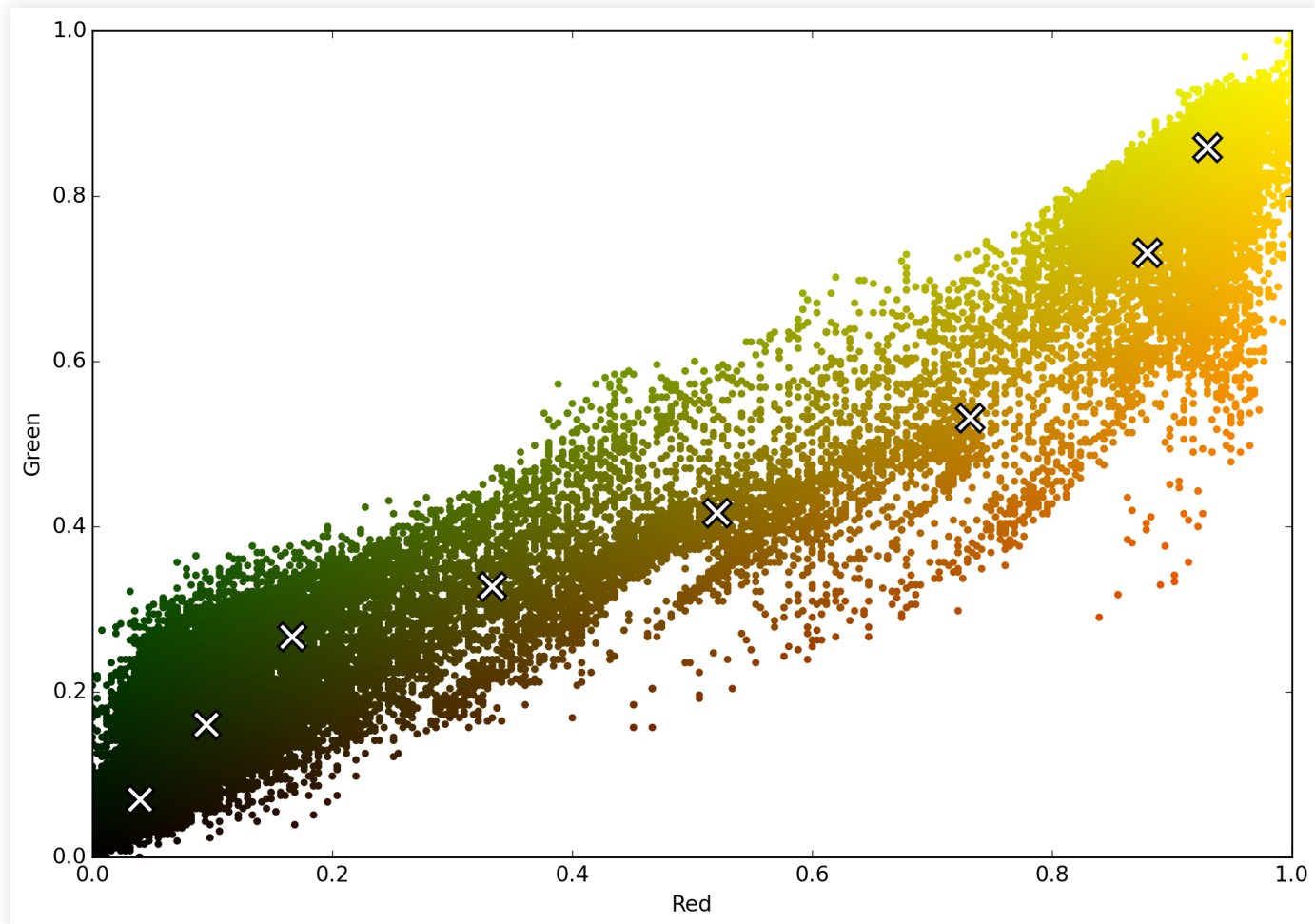
# K-means color quantization

- Compress from 24 bits to 6 bits



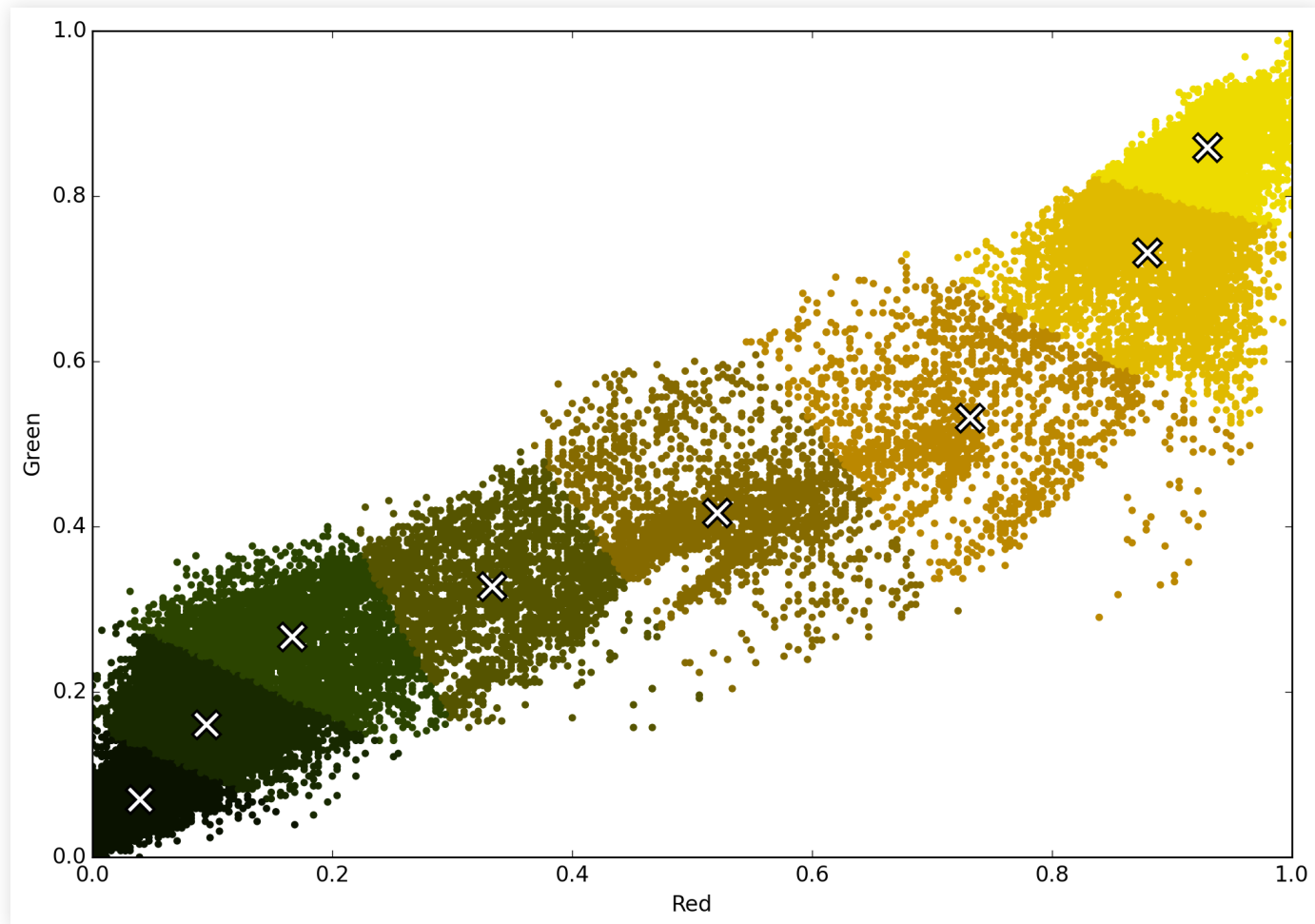
# K-means color quantization

- Compress more, 8 centroids



# K-means color quantization

- Convert pixel colors to centroid



# K-means color quantization

- Compress from 24 bits to 3 bits





## Summary

## Summary

- Clustering: grouping data by similarity
- Hierarchical vs Partitional, Complete vs Partial
- Exclusive, Overlapping, Fuzzy or Probabilistic
- Types of clusters: Prototype, Contiguity, Density
- K-means: prototype, partitional
- EM algorithm: estimate, maximize, repeat

## Further reading

- Bishop, Section 9.1 (and 9.3, intro, for EM)
- Alpaydin, Section 7.3
- Marsland, Chapter 9 (also relates k-means to SOM)

